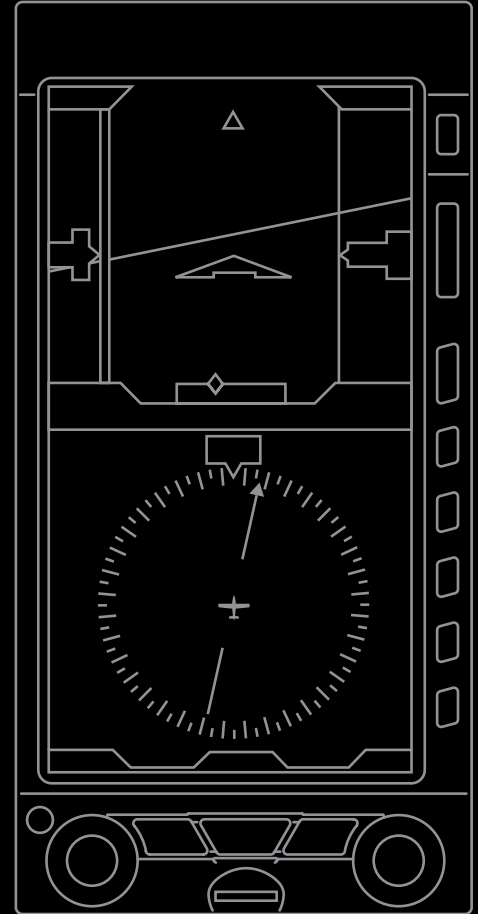


# EVOLUTION

FLIGHT DISPLAY

## EFD1000 PFD Pilot's Guide

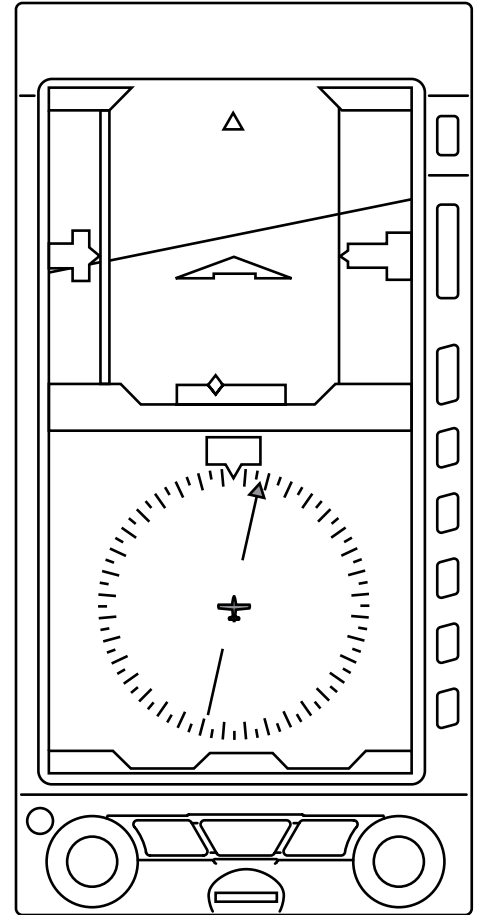




# EVOLUTION

FLIGHT DISPLAY

## EFD1000 PFD Pilot's Guide



# Document Revisions

Revision	Description of Change
* Legacy P/N revision is displayed above the new CI number Revision	
A	Initial Release
B	Layout Update.
C* ( )	<p>**Part number change: old part number A-01-184-00 REV C; new part number 091-00005-001 REV ( ).</p> <p>Grammatical, pictorial, and technical corrections and updates.</p> <p>Revised to update for software version 1.1, which include:</p> <ul style="list-style-type: none"> <li>New start-up splash screen.</li> <li>Failure message for RSM and Config Module link.</li> <li>Brightness changes: <ul style="list-style-type: none"> <li>• Auto brightness range 1% - 70%</li> <li>• Manual brightness range 1% - 100%</li> <li>• During internal battery operation, brightness capped at 40% for Auto mode and 70% for Manual mode.</li> <li>• When temperature is above <math>\geq 70^{\circ}\text{C}</math>, brightness capped at 30% for Auto mode and 70% for Manual mode.</li> </ul> </li> </ul> <p>Main Menu, System Status Page added Unit S/N.</p> <p>Wind Speed and Direction Degrees do not display when:</p> <ul style="list-style-type: none"> <li>• When aircraft is on the ground.</li> <li>• When wind speed is <math>\leq 10</math>. Additionally, the Wind Arrow does not display.</li> </ul> <p>Added Title page, Revision page and Index</p>
A	

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The FAA has approved the EFD1000 Pro PFD under the following TSOs:

TSO-C2d, TSO-C3d, TSO-C4c, TSO-C6d, TSO-C8d, TSO-C10b, TSO-C106, TSO-C113

The following certification levels also apply to this product:

Environmental Certification Level: RTCA DO-160E

Software Certification Level: RTCA DO-178B Level C

This Pilot's Guide provides information on the use and operation of the Evolution Flight Display 1000 Pro Primary Flight Display (EFD1000 Pro PFD). This guide is current as of the Date Published. Specifications and operational details are subject to change without notice when using an earlier or later software version. Please visit the Aspen Avionics web site for the most up-to-date Pilot's Guide.

Installation of the EFD1000 Pro PFD in a type-certificated aircraft must be performed in accordance with the latest revision of the Aspen Avionics EFD1000 Pro PFD Installation Manual, document number A-01-126-00 /

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*This warranty gives you specific legal rights, and you may also have other rights which vary from State to State.*

# Conventions

The following conventions, definitions, terminology, and colors are used in this manual and on the EFD1000 PFD.

## Covered Functionality

This guide covers all the functionality available in the EFD1000 Pro PFD.

## Terminology

**Figure 1** shows a typical EFD1000 Pro PFD display. This guide uses the terminology listed in **Table 1** when referring to specific parts of the EFD1000 Pro PFD. **Chapter 4** provides an in-depth discussion and step-by-step instructions for all the available functionality of the EFD1000 Pro PFD.



Figure 1 EFD1000 PFD Display, Knobs , Buttons, and Keys

Term	Example
1	Attitude Display
2	Data Bar
3	Navigation Display
4	Knobs Left (CRS) Knob, Right (HDG) Knob
5	Buttons Left Button, CDI Button, Right Button
6	Keys REV Key, RNG Key, MENU Key, Bezel Key(s) (1-5)

Table 1 EFD1000 PFD Display, Knobs , Buttons, and Keys



## Color Philosophy

**Table 2** provides the operational philosophy of color usage on the EFD1000 PFD display.

COLOR	PURPOSE
RED	Used to indicate flight envelope and system limits, and for warning annunciations that require immediate pilot recognition and which may require immediate pilot correction or compensatory action.
AMBER	Used to indicate abnormal information sources, and for caution information that requires immediate pilot awareness and for which subsequent pilot action may be required.
MAGENTA	Used for pilot-selectable references (bugs) enabled for editing, for depicting the active GPS navigation leg on a moving map display, and for depicting the flight director bar.
CYAN	Used to indicate editable values that are not currently selected for editing, and is also used for bearing pointers depictions.
GREEN	Used for navigation information or mode data related to or provided by the navigation source currently selected for display on the Course Deviation Indicator (CDI) (i.e. navigation deviations, equipment operating state, waypoint information).
WHITE	Used to show primary flight data (e.g. IAS, ALT, HDG), scales, etc.
GRAY	Used to show supplemental flight data.
BLUE	Used to indicate the sky.
BROWN	Used to indicate the ground.



### NOTE

*As the number of colors used on the display is limited, to ensure adequate color differentiation under all lighting conditions, there are a few cases where a given color is used in a slightly different context than described in Table 2.*

Table 2 Color Guide

## Warnings, Cautions, and Notes

Where applicable warnings, cautions, and notes are given. Aspen Avionics uses the following icons and definitions (**Table 3**).




Icon	Definition
 <b>Warning</b>	Emphasizes a crucial operating or maintenance procedure, which, if not strictly observed, could result in injury to, or death of, personnel or long term health hazards. Indicates a hazard which may require immediate corrective action.
 <b>Caution</b>	Indicates an essential operating or maintenance procedure, which, if not strictly observed, could result in damage to, or destruction of equipment. Indicates the possible need for future corrective action.
 <b>Note</b>	Highlights an important operating or maintenance procedure, condition, or statement. Safe operation.

Table 3 Warning, Caution, and Note

## Example Graphics

Most of the example graphics and screen shots used throughout this Pilot's Guide & Reference are based on flying the ILS 16R instrument approach into Reno/Tahoe International Airport (KRNO) in Reno, Nevada, USA. Those images with the airplane in a right bank show the airplane completing the procedure turn in-bound to intercept the Localizer, descending through 8,660 feet to the target altitude of 8,500 feet. The other main group of images, showing the airplane straight and level, are earlier in the approach, tracking outbound for the procedure turn.

## Pilot Familiarity

While the EFD1000 is reasonably intuitive and easy to use, some familiarity with Electronic Flight Instrument Systems (EFIS) and Horizontal Situation Indicators (HSI) is required. Aspen Avionics strongly recommends that new users of the EFD1000 get some dual instruction from an experienced instrument CFI, and spend some time becoming familiar with the PFD in day VFR conditions with a safety pilot, before flying in actual instrument meteorological conditions (IMC). To reduce pilot workload, the use of autopilot (when available) is strongly encouraged.



## Chapter 1

### Welcome & Introduction

Welcome to Aspen Avionics' Evolution Flight Display (EFD) system, the most flexible, expandable, and upgradable Electronic Flight Instrument System (EFIS) available for General Aviation aircraft. Designed to replace traditional, mechanical primary flight instruments—in whole or in part, all at once, or in phases. This modularity and upgradability allows the system to grow with you and your airplane, over time and affordably.

The EFD system is built around the EFD1000 Display Unit, which replaces a vertical pair of your six primary flight instruments. The EFD1000 has a bright, high-resolution, six-inch diagonal LCD display, and a number of knobs and buttons the pilot uses to control the system. The three-inch diameter, four-inch deep can on the back of the display slides into existing panel cutouts (where the top mechanical instrument used to be) (**Figure 1-1**).



Figure 1-1  
EFD1000 PFD Display Unit



Figure 1-2 Single-tube EFD1000 PFD system



Figure 1-3 Two-tube system: PFD &amp; MFD

The center of the EFD system is the EFD1000 Primary Flight Display (PFD), which replaces the traditional, mechanical Attitude Indicator (AI) and Directional Gyro (DG) or Horizontal Situation Indicator (HSI) (**Figure 1-2**). The PFD is available in three models—the Pilot, Pro and ATP—each with increasing levels of features and capabilities, and each lower model is upgradable through software to the more capable models.

Add a second EFD1000 configured as a Multi-Function Display (MFD) (**Figure 1-3**), replacing the altimeter and Vertical Speed Indicator (VSI), and you'll double the capabilities of your system, while also providing complete redundancy and backup to your PFD. The EFD1000 MFD contains the same AHRS, ADC, and I/O capabilities as the PFD for full redundancy, and can assume the role of PFD should your main PFD ever fail.

You can even add another MFD, replacing the Airspeed Indicator (ASI) and turn coordinator, to round out a complete “six-pack” replacement and gain even more capability and flexibility (**Figure 1-4**). When you are ready to upgrade, simply contact an Aspen Avionics Authorized Dealer for more information.



Figure 1-4 Three-tube system: PFD & dual MFDs

This Pilot's Guide covers the EFD1000 Pro PFD models. These systems are powerfully flexible, and can be configured in a variety of ways, depending on the other aircraft systems with which they are integrated.



## NOTE

*Please spend some time with your avionics installer to understand exactly how your PFD is installed and configured in your particular aircraft, to understand the features and capabilities available to you, and to understand how various aircraft system failures and abnormalities may affect your EFD1000 PFD.*

## 1.1. System Overview

The EFD1000 Pro PFD system typically consists of four components:

1. EFD1000 Display Unit
2. Configuration Module (CM)
3. Remote Sensor Module (RSM)
4. Analog Converter Unit (ACU)

The ACU converts older analog signals and interfaces to the industry-standard digital ARINC 429 interface, which is the native language of the EFD1000. In some installations, generally when the aircraft is not equipped with an autopilot and has only digital GPS/nav/comms, the ACU may be omitted.

The system architecture in **(Figure 1-5)** shows the relationships of the PFD, RSM, Configuration Module and ACU.

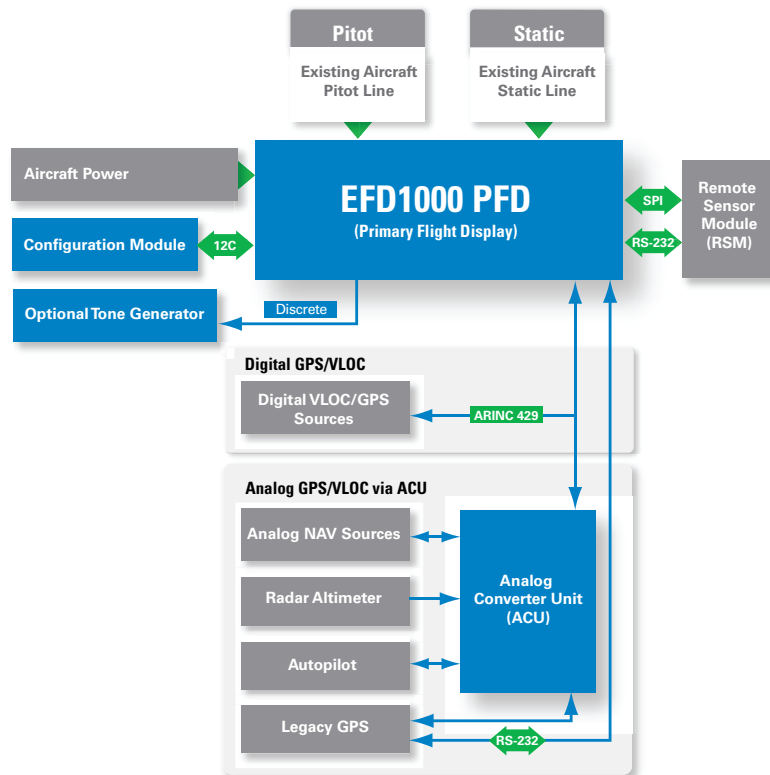


Figure 1-5 EFD 1000 System Architecture



### 1.1.1. EFD1000 Display Unit

The EFD1000 system unit is a digital system that consists of a high resolution 6" diagonal color LCD display, user controls, photocell, and Micro SD data card slot. The three-inch diameter, four-inch deep can on the back of the display contains a non-removable electronics module which includes:

- A Sensor Board with solid-state Attitude and Heading Reference System (AHRS) and digital Air Data Computer (ADC).
- A Main Application Processor (MAP) board with Central Processing Unit (CPU), graphics processor and system memory.
- An Input-Output Processor (IOP) board for integrating communications with other aircraft systems.

Also on the rear of the unit are **(Figure 1-6)**:

- An access cover for removing and replacing the built-in backup battery.
- Pneumatic connections to the aircraft's pitot and static systems.
- 44-pin D-sub connector for electrical connections to the EFD1000.
- A cooling fan, to cool the electronics and LCD backlights.

The PFD mounts to the front surface of most instrument panels.

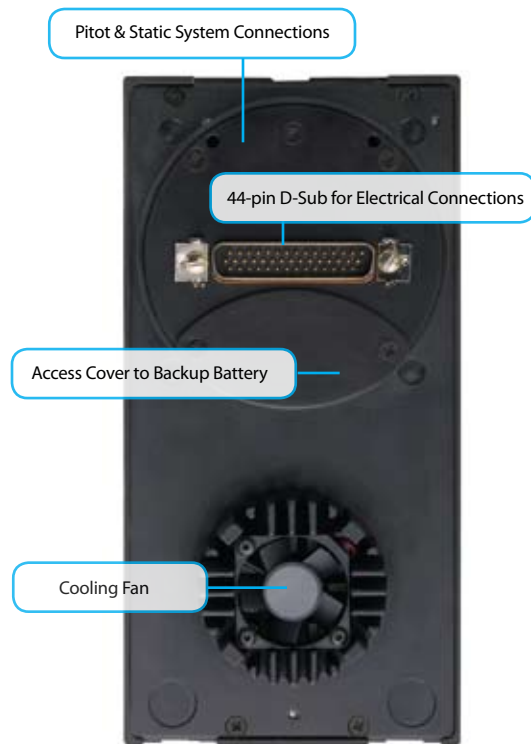


Figure 1-6 PFD Rear Connections

### 1.1.2. Configuration Module (CM)

The Configuration Module contains an EEPROM device that retains system configuration and calibration data and provides two primary functions:

- Retains aircraft-specific configuration information, calibration data, and user settings, allowing the PFD to be swapped for service purposes without re-entering or re-calibrating the installation.
- Contains a license key that configures the PFD software features.

The CM is typically attached to the wire bundle coming out of the D-sub connector on the system unit.

### 1.1.3. Remote Sensor Module (RSM)

The Remote Sensor Module (RSM) is an integral part of the EFD1000 system, and works together with the display unit sensors as part of the AHRS and ADC. The RSM looks and mounts like a GPS antenna, and is mounted on the exterior of the fuselage, typically aft of the cabin.

The RSM contains the following sub-systems:

- 3D magnetic flux (heading) sensors.
- Orientation accelerometers.
- Outside Air Temperature (OAT) sensor.
- Emergency backup GPS engine and antenna.

The RSM communicates with the EFD1000 system unit via a digital cable connection.

### 1.1.4. Analog Converter Unit (ACU)

The Analog Converter Unit (ACU), included with most Pro PFD systems, enables the all-digital EFD1000 system to interface to analog avionics when required. The ACU converts multiple analog interfaces to the digital ARINC 429 buses supported by the PFD. Control parameters, such as desired heading, are also sent from the PFD to the ACU for conversion to analog format for autopilot support. The ACU is required when any of the following capabilities are required in a Pro PFD installation:

- Interface to supported autopilots.
- Interface to conventional VHF navigation radios.
- Interface to legacy (non-ARINC 429) GPS navigators.
- Interface to supported radar altimeter decision height annunciations.

If ARINC 429-based digital radios, such as the Garmin 400/500-series GPS/nav/comm radios, are installed in the aircraft, and no other aircraft interfaces are desired, the ACU is not required.



## Chapter 2

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### Controls and Display

The EFD1000 Pro PFD is a flat-panel LCD primary flight instrument that presents the pilot on a single display with all the information delivered by the traditional six-pack of mechanical instruments: Airspeed, Attitude, Altitude, Turn Coordinator, Heading Indicator (or HSI) and Vertical Speed Indicator (VSI). Modern technology and standard EFIS symbology enable the consolidation of all six instruments into a single display, tightening the pilot's instrument scan and reducing pilot workload.

The Pro PFD is a single vertical instrument that replaces the existing Attitude Indicator and Heading Indicator/HSI. The display is divided into three parts: an upper Attitude Display, a lower Navigation Display, and a Data Bar in the middle of the upper and lower halves. The Attitude and Navigation displays are highly customizable — from stripped-down, minimalist presentations, to dense, information-rich displays — depending on pilot preference and phase of flight.

This Chapter gives an overview of all the instruments, information, and controls of the EFD1000 Pro PFD. The next two pages show and identify each element of the display and each control with a Reference (Ref.) number and description. Throughout this section, notes like “(Ref. 27)” refer to **Table 2-1** and **Figure 2-2**. For more detailed information on any specific part, see the **Reference Guide, Chapter 4**.



Figure 2-1 EFD1000 Actual Display

## 2.1. Controls & Display Orientation

CONTROLS		ATTITUDE DISPLAY	
1	Reversion and Power Button	16	Attitude Display
2	Range Button	17	Aircraft Symbol
3	Menu Button	18	Single-Cue Flight Director (optional)
4	TPS Hot Key - Tapes On/Off	19	Roll Pointer
5	MIN Hot Key - Minimums On/Off	20	Slip/Skid Indicator
6	360/ARC Hot Key - HSI View	21	Altitude Tape
7	MAP Hot Key - Map Declutter	22	Selected Altitude Field
8	GPSS Hot Key - GPS Steering On/Off	23	Altitude Alert
9	Right Control Knob	24	Altitude Drum/Pointer
10	Double-Line Bearing Pointer Source Select	25	Altitude Bug
11	CDI Source Select	26	Decision Height Annunciation
12	Single-Line Bearing Pointer Source Select	27	Selected Minimums Field
13	Left Control Knob	28	MINIMUMS annunciation
14	Automatic Dimming Photocell	29	LDI Navigation Source Indication
15	Micro SD Card Slot	30	Airspeed Indicator Tape
		31	Selected Airspeed Field
		32	Airspeed Bug
		33	Airspeed Drum/Pointer
		34	Vertical Deviation Indicator
		35	Lateral Deviation Indicator

DATABAR		
36	True Airspeed (TAS)	
37	Barometric Pressure Setting Field	
38	Wind Direction and Speed	
39	Wind Direction Arrow	
40	Outside Air Temperature (OAT)	
41	Ground Speed (GS)	
NAVIGATION DISPLAY		
42	Navigation Display	55 Vertical Speed Tape
43	Ownship Symbol	56 Single-Line Bearing Pointer
44	Course Pointer	57 Single-Line Bearing Pointer Source
45	TO/FROM Indicator	58 Single-Line Source Info Block
46	Rate of Turn Indicator	59 Double-Line Bearing Pointer
47	Track Marker	60 Double-Line Bearing Pointer Source
48	Magnetic Heading	61 Double-Line Source Info Block
49	Selected Course (CRS) Field	62 CDI Navigation Source
50	Selected Heading Field	63 CDI Source Information Block
51	Heading Bug	64 Left Control Knob State
52	Course Deviation Scale	65 Right Control Knob State
53	Course Deviation Indicator	66 Hot Key Legend
54	Vertical Speed Digital Value	

Table 2-1 EFD1000 Pro PFD Components

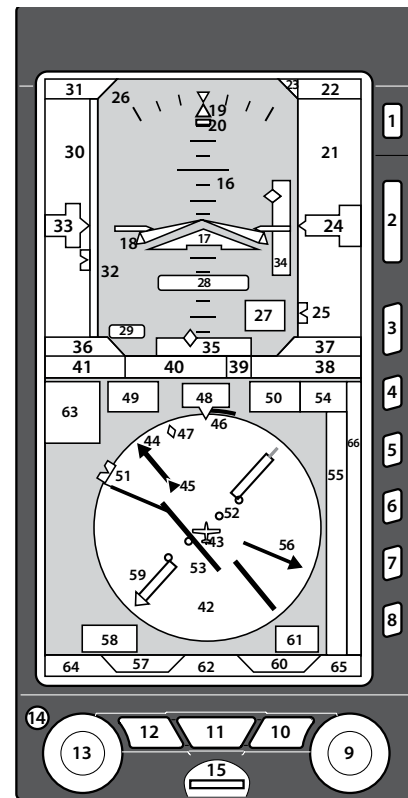


Figure 2-2 EFD1000 Display Elements

## 2.2. Controls

The primary means for the pilot to control the EFD1000 are the two knobs and three buttons at the bottom of the display. The knobs control setting CRS and HDG, and additional bugs and altitude settings. The three buttons control selection of navigation sources for the CDI and bearing pointers.

Additionally, five hot keys to the right of the Navigation Display toggle various features on and off. The function of each is indicated by the label on the screen to the left of each button. Three additional buttons above the hot keys control entering and exiting the Menu system, setting the Map range, and reversion or manual power control.

### 2.2.1. Left and Right Knobs

The Left and Right Knobs are both of the push and rotate type. Pressing the knob activates it for control, and subsequent presses cycle through its available control functions in round-robin sequence.

Each knob has an inactive Home state, to which it returns automatically after 10 seconds of inactivity. The inactive state is designed to prevent inadvertent adjustment of a setting. The Left Knob Home state is CRS, and the Right Knob Home state is HDG. A single push of the knob activates the Home state (CRS or HDG) for editing.

To change an available setting, repeatedly press the appropriate knob until the desired function appears in magenta above the knob (the setting you are changing will also appear in magenta on the display). With a little practice, you'll soon know exactly how many presses it takes from the Home state to get to what you want to set.



When the function you want to set is shown in magenta, dial the knob left or right to set the desired value, or press and hold the knob to synchronize (SYNC) the setting. Once set, you can either press the knob again to advance to the next function you'd like to set, or you can do nothing and in 10 seconds the knob will return to its home state (CRS or HDG).

### 2.2.1.1. Right Knob Functions

The Right Knob Home state is **Heading (HDG)**. The Right Knob is also used to set the **Altitude Alerter selected altitude (ALT)**, **barometric pressure (BARO)** and **instrument approach minimums (MIN)**. Successive presses of the right knob will cycle through HDG-ALT-BARO-MIN in round-robin sequence.

From the inactive Home state (HDG shown in cyan above the right knob):

- Press once to set the heading bug (HDG) (**Refs. 50 and 51**).
- Press twice to set target altitude (ALT) (**Refs. 22 and 25**).
- Press three times to set barometric pressure (BARO) (**Ref. 37**).
- Press four times to set approach minimums (MIN) (**Ref. 27**).

### 2.2.1.2. Left Knob Functions

The Left Knob Home State is **Course (CRS)**. The Left Knob is also used to set the **Airspeed Bug (IAS)**.

From the inactive Home state (CRS shown in cyan above the left knob):

- Press once to set the course (CRS) (**Refs. 44 and 49**, and see note at right about Auto Course).
- Press twice to set the airspeed bug (IAS) (**Refs. 31 and 32**).

#### NOTE

MIN will only be shown if the MIN function is already active (the MIN label by the second Hot Key (**Ref. 5**) is shown in green, and the MIN value is shown on the Attitude Display (**Ref. 27**). If the MIN function is inactive (label in gray), pressing the MIN Hot Key will both activate the function and immediately make it available for setting.

#### NOTE

When the CDI navigation source is selected to a GPS receiver, and Auto Course is enabled in the main menu (see **Section 4.3.6**), the course is set automatically by the GPS and is not pilot-adjustable. This case will be indicated by the CRS field and Knob label being shown in Green with an inverse "A". In this case, pressing the Left Knob will enable you to set only the airspeed bug (IAS).



Figure 2-3  
Left and Right Knobs and  
Corresponding Fields

### 2.2.1.3. SYNC Function

#### Control Knob SYNC Function (Figure 2-3)

1. Repeatedly press the control knob until the control knob label shows the value you want to set in magenta.
2. Press and hold the control knob for approximately one (1) second to synchronize the setting according to the rules shown in **Table 2-2**.
3. After 10 seconds of inaction, the knob reverts to its Home state (CRS or HDG), and the labels and field are shown in cyan (inactive).

#### Right Knob

	SYNC Action	
<b>1</b>	ALT	Bug and alerter are set to the current altitude.
<b>2</b>	MIN	Set to the current altitude.
<b>3</b>	BARO	Set to 29.92 InHg or 1013 mB.
<b>4</b>	HDG	Set to the current heading.
<b>5</b>	Right Knob - Current Field Label [HDG] (cyan indicates field is inactive)	

Left Knob			
	SYNC Action		
6	IAS	Set to the current Indicated Airspeed.	
7	CRS	VOR navigation	Set to the reciprocal value of the current VOR radial. The deviation bar centers with a "TO" indication.
		ILS navigation	Current aircraft heading.
		GPS	Set to equal the bearing to the GPS active waypoint. The deviation bar centers with a "TO" indication. (AUTOCRS must be disabled.)
		GPS AUTOCRS enabled	No effect.
8	Left Knob - Current Field Label  [CRS] (cyan indicates field is inactive, green with inverse A indicates Auto Course is enabled)		

Table 2-2 Left and Right Knob Sync Description



Figure 2-4  
Activating the HDG field to edit



Figure 2-5  
Editing the HDG field



Figure 2-6  
HDG field updated and inactive

### 2.2.1.4. Using the Knobs (Example)

#### How to Set the Heading Bug (HDG)

1. From the Home state (at least 10 seconds since last using the Right Knob), press the right control knob once to select HDG for editing. The control knob label (HDG), the Heading Bug, and the Selected Heading field will all turn magenta (**Figure 2-4**).
2. Rotate the control knob to the desired heading value, shown both by the position of the Heading Bug and the numeric value in the Selected Heading field (**Figure 2-5**).
3. After 10 seconds of inaction, the knob reverts to its Home state (HDG), and the Heading Bug and Selected Heading field value are shown in cyan (inactive) (**Figure 2-6**).

### 2.2.2. Navigation Source Select Buttons

The three buttons on the bottom of the EFD1000 PFD allow the pilot to select the navigation source for the CDI and Bearing Pointers (**Figure 2-7**). See **Section 4.3** for detailed information on the CDI and Bearing Pointers.

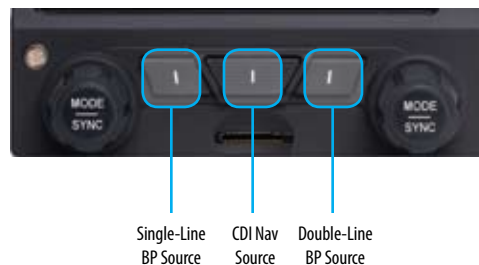


Figure 2-7  
CDI and Bearing Pointer Source Select Button

### 2.2.2.1. CDI Nav Source Control

The center button of the three buttons between the control knobs at the bottom of the EFD1000 Pro PFD (**see Figure 2-7**) is the CDI Nav Source Select Button. It selects which of the available navigation sources will couple to the CDI, which in turn couples to the autopilot (if available). Each press of the CDI Nav Source button selects the next available nav source, cycling through all available sources in round-robin sequence. The currently coupled CDI nav source is displayed directly above the CDI Nav Source Select Button.

The available nav sources are configured when the EFD1000 is installed (depending on what is installed in the aircraft and connected to the EFD1000). The available nav source choices are: GPS1, ~~GPS2~~, VLOC1 and ~~VLOC2~~.

If a nav source is configured to be available, but is not currently putting out valid navigation data, its identifier will be shown with a red slash through it, and the CDI bar will not be shown with the Course Pointer. The pilot will be able to select that invalid source, but no navigation data will be provided.

When one or more of the connected nav sources is a combined GPS/Nav device (e.g., some of the Garmin 400/500-series), the list of nav sources available for selection will be determined by the current CDI mode of that navigator.

#### NOTE

When GPS is selected as the nav source, but no active waypoint is programmed in the GPS navigator, that source will be shown as invalid, until an active flight plan or direct-to waypoint is programmed into the GPS.

#### NOTE

For example, with a Garmin GNS-430 installed as the #1 navigation source, if "GPS" is shown immediately above the CDI key on the GNS-430, then the EFD1000 will show GPS1 as an available nav source. If the pilot presses the CDI key on the GNS-430 so that VLOC is now displayed on the GNS-430, then the EFD1000 will show VLOC1 as the available nav source and GPS1 cannot be selected.

### 2.2.2.2. Bearing Pointer Nav Source Control

The two outer buttons between the control knobs are the Bearing Pointer Nav Source Select Buttons (see Figure 2-7). The left-hand button controls BRG1 (the single-line bearing pointer) and the right-hand button controls BRG2 (the double-line bearing pointer), and each controls which nav source is coupled to that bearing pointer.

The bearing pointers act like a conventional RMI (Radio Magnetic Indicator): the needle points to the station. Unlike a conventional RMI, EFD1000 bearing pointers can also point to the active waypoint of a GPS navigator, whether that is a VOR, NDB, airport, intersection, or missed approach point.

Each bearing pointer can be coupled to any of the available navigation sources: GPS1, GPS2, VLOC1, or VLOC2 (depending on configuration), or to none. Each press of the Bearing Pointer Nav Source Select Button selects the next available nav source, cycling through all available nav sources and none, in round-robin sequence. The currently coupled nav source is displayed directly above the Select Button; blank indicates that no nav source is selected and the bearing pointer will not be displayed.

If the selected nav source is a valid choice, but no usable nav data is being received (e.g., the VOR station is out of range), the bearing pointer will not be displayed, or the VLOC is tuned to a localizer frequency.

### 2.2.3. Hot Keys

The five keys along the lower right of the EFD1000 PFD function as either single-action Hot Keys for frequently used commands or as Menu selection keys when the Main Menu has been activated (**Figure 2-9, page 2-12**).

Hot Key functions are accessible anytime, except when the Menu is active. Each Hot Key provides instant access to the assigned command as listed in **Table 2-3**. Each press of a Hot Key toggles between the settings that key controls. The TPS, MIN and GPSS Hot Keys are either ON, with a green label, or OFF, with a gray label. The ARC/360 Hot Key label indicates which compass mode is currently active on the Navigation Display.

The MAP Hot Key displays the GPS flight plan, legs, waypoints, and base map on the Navigation Display, with one of four levels of declutter, and turns off the map. Pressing the MAP key cycles through these available options. When the MAP is turned off, or is unavailable, the label is gray.

When the function a Hot Key controls is unavailable or invalid, the label displays with a vertical red line, as shown in **Figure 2-8**.



Figure 2-8  
Invalid Hot Key Legend

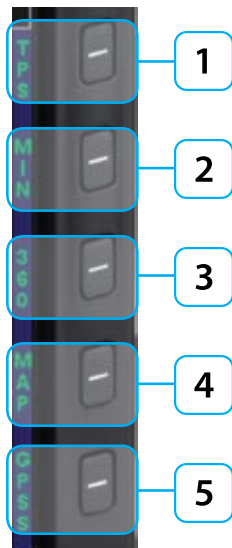


Figure 2-9 Hot Keys

Figure 2-10  
Map Level HIGHFigure 2-11  
Map Level MEDIUMFigure 2-12  
Map Level LOWFigure 2-13  
Map Level FP ONLYFigure 2-14  
Map Level OFF

HOT KEY		DESCRIPTION	OPTIONS	
1	TPS	Displays or hides air data tapes (airspeed and altitude) <sup>1</sup> (see	<b>TPS</b>	Tapes displayed
			<b>TPS</b>	Tapes hidden
2	MIN	Enables and displays, or disables and hides, Minimums Alserter (see <b>Section 4.1.3.4</b> ).	<b>MIN</b>	Minimums displayed and alserter enabled <sup>2</sup>
			<b>MIN</b>	Minimums alserter disabled
3	ARC/ 360	Toggles between 360 and ARC modes of Navigation Display (see <b>Section 4.3.1</b> ).	<b>ARC</b>	ARC Compass Mode
			<b>360</b>	360° Compass Mode
4	MAP	Selects Map display and feature level <sup>3</sup> (see Section 4.3.12.1).	<b>MAP</b>	High (see <b>Figure 2-10</b> )
			<b>MAP</b>	Medium (see <b>Figure 2-11</b> )
			<b>MAP</b>	Low (see <b>Figure 2-12</b> )
			<b>MAP</b>	Flight Plan Only (see <b>Figure 2-13</b> )
			<b>MAP</b>	Off (see <b>Figure 2-14</b> )
5	GPSS	Toggles between GPS Steering (GPSS) Mode and HDG mode for Autopilot/Flight Director <sup>4</sup> (see <b>Section 4.6.1</b> ).	<b>GPSS</b>	GPSS On
			<b>GPSS</b>	GPSS Off, HDG mode active

Table 2-3 Hot Key Description

1. Available only in those installations where the original airspeed indicator and altimeter remain in their primary flight instrument positions.
2. When Minimums display and alerting is initially enabled, the minimums value is immediately selected for editing.
3. Flight plan legs and waypoints display available in all installations including a GPS navigator. Base map display of nearby waypoints available with all ARINC 429 GPS navigators and some RS-232 GPS navigators.
4. GPSS available only with ARINC 429-based navigators.



## 2.2.4. Menu Key

The MENU Key is used to access the EFD1000 PFD's Menu system to change options, and also to change the EFD1000's LCD brightness controls.

### 2.2.4.1. Using the Menus

Press the MENU Key to activate the Menu system (**Ref. 3**). The current Menu Page Name displays on the bottom center of the Navigation Display. Directly below the Menu Page Name is a segmented menu page bar, giving a graphical representation of the current page relative to the total number of menu pages. The current menu page number displays in the lower right of the Navigation Display.

Menu Page 1, General Settings, is the one most commonly used in flight. It enables the pilot to enable or disable AUTO COURSE SELECT mode, to display or hide the V-speeds on the airspeed tape, and to choose the type of CDI display for ARC mode. The other menu pages are used for V-speed and map customization, for abnormal power management, and for displaying product version information.

The Menu system operates either in Navigation or Edit mode, as indicated by the label directly above the Right Knob. When the MENU key is first pressed, the Menu system is in Navigation mode, indicated by the magenta label SEL PAGE directly above the Right Knob (**Figure 2-15**). When in Navigation mode, rotating the Right Knob navigates through the menu pages. Rotate the Right Knob clockwise to advance to the next menu page. Rotate the Right Knob counterclockwise to return to previous menu page.



Figure 2-15  
Menu Navigation Mode



Figure 2-16  
Menu Edit Mode

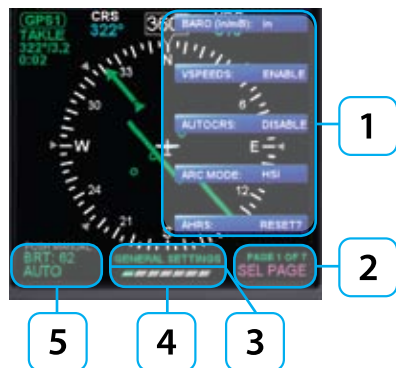


Figure 2-17 Menu

Each Menu page displays up to five selectable options, each adjacent to one of the five Hot Keys (which double as Menu Select keys in the menu system). After navigating to the Menu Page containing the option you want to change, press the Menu Key adjacent to that option label, which initiates the menu's Edit mode. When the Menu is in Edit mode, the label EDIT VALUE, displays above the Right Knob in magenta (**Figure 2-16**), and the label of the item selected for editing is also shown in magenta. Rotate the Right Knob to change the value of the selected item. When done, either select another displayed option to change, or push the Right Knob to exit Edit mode and return to Navigation mode to select another menu page.

When you are finished changing menu options, press the MENU key again to exit the menu system (**Figure 2-17**).

- 1 Menu
- 2 Menu Page number and mode (Navigation mode shown)
- 3 Menu Page Name
- 4 Menu Page graphical bar
- 5 Brightness Control (see **Section 2.2.4.2**)

The menu text will display in one of the four colors listed and described in **Table 2-4**.

DISPLAY TEXT	DESCRIPTION	DISPLAY
<b>WHITE</b>	Editable option	See <b>Figure 2-18</b>
<b>MAGENTA</b>	Editable option enabled	See <b>Figure 2-19</b>
<b>GREEN</b>	Non-Editable or “Status Only”	See <b>Figure 2-20</b>
<b>GRAY</b>	Disabled	See <b>Figure 2-21</b>

Table 2-4 Menu Text



#### NOTE

*These steps are provided as a basic overview. Each menu command is covered in detail further in **Chapter 5**.*

### Access and Navigate the Menus

1. Push the MENU key. The Menu displays on the Navigation Display adjacent to the Hot Keys (**Figure 2-22**).
2. Rotate the Right Knob to navigate through the different pages of the menu. Rotating the Right Knob clockwise advances forward one menu page at a time. Rotating the Right Knob counterclockwise advances backward one menu page at a time.
3. When finished, press the MENU key to exit the Main Menu.

AUTOCRS: DISABLE

Figure 2-18  
Menu Text - Editable

AUTOCRS: DISABLE

Figure 2-19  
Menu Text - Enabled

EXT PWR: 13.8V

Figure 2-20  
Menu Text - Status Only

Vle: 129

Figure 2-21  
Menu Text - Disabled



Figure 2-22  
Menu Display

**NOTE**

Pressing the Right Knob returns to navigation mode and allows selection of other menu options on different pages. Pressing another menu key on the current menu page saves any changes made, and activates the newly selected option for editing.



Figure 2-23  
EDIT VALUE Displays Above Right Knob

**NOTE**

Upon reaching the end of a list of editable menu options, continued rotation of the knob shall not result in the continuous “wrapping” through the available editable menu options.

### Edit Main Menu Items

1. Access the Main Menu.
2. Navigate to the desired menu page.
3. Push the Menu Key of the desired option. The menu label turns magenta and the EDIT VALUE label displays above the Right Knob (**Figure 2-23**).
4. Rotate the Right Knob to the desired value.
5. Push the Right Knob to return to menu navigation mode.
6. Push the MENU key to exit the Main Menu.

#### 2.2.4.2. Changing LCD Display Brightness

When the MENU key is pressed and the menu system is active, the Left Knob can be used to adjust the EFD1000 display brightness.

By default, the LCD brightness operates in AUTO mode, and is adjusted based on photocell sensing of ambient lighting conditions. When the MENU is active and the LCD is in AUTO, the word AUTO and a brightness level of 1-100 will be displayed in green above the Left Knob.

To override the AUTO brightness setting, press the Left Knob once to switch into Manual mode, and then rotate the Left Knob to set the brightness to the desired level. To return to AUTO brightness control, press the Left Knob again.

LCD MODE	DESCRIPTION	DISPLAY
<b>Automatic BRT AUTO</b>	LCD backlight intensity is automatically adjusted based on the current light conditions sensed by the Automatic Dimming Photocell. The maximum intensity in Automatic mode is 70%.	See <b>Figure 2-24</b>
<b>Manual BRT ADJUST</b>	Allows the pilot to adjust the LCD backlight intensity manually, from 1--100%.	See <b>Figure 2-25</b>

Table 2-5 Brightness Control

### 2.2.5. Range Button

When the MAP is enabled, the RNG (Range) button is used to zoom in or out in scale to display more or less of the map. Range can be adjusted from 2.5 to 200 nautical miles. Press the top or (+) part of the RNG key to increase map range. Press the bottom or (–) part of the RNG key to decrease map range.

### 2.2.6. REV Button

In multi-tube EFD1000 systems, the red REV button activates Reversionary mode, providing backup should one of the tubes fail. The REV button can also be used to override automatic power control in abnormal or emergency situations. See **Chapter 6** for more details.

### 2.2.7. Cleaning the Display Screen

The EFD1000 PFD display is an LCD screen that is prone to damage from scratches, smudging, and clouding caused by the use of improper cleaning agents and harsh cloths. Use care when cleaning, using the following tips:

- Only clean the display when the unit is off.
- Use a clean, soft, lint free cloth dampened with a 50/50 solution of isopropyl alcohol and water, a pre-moistened lens cleaning tissue like Bausch & Lomb Sight Savers®, or a cleaning solution made especially for LCD displays.
- Never spray any cleaning solutions directly onto the screen, spray it into the cleaning cloth.
- Gently wipe the screen in a circular motion. Do not press hard on the cloth.
- Remove all excess moisture to prevent damage of the EFD1000 PFD display.
- The EFD1000 PFD display should be dry before powering the unit on.

#### NOTE

*Use caution when using isopropyl alcohol as it is flammable. Using any other chemicals or materials voids the warranty.*



Figure 2-24  
Display Brightness in BRT AUTO Mode



Figure 2-25  
Display Brightness in BRT ADJUST Mode



Figure 2-26 EFD1000 Pro PFD Display Areas

## 2.3. Display

The EFD1000 Pro PFD replaces the existing Attitude Indicator and HSI or DG in the center of the primary flight instrument cluster. Like the instruments it replaces, the top half presents an Attitude Display and the bottom half presents a Navigation Display (**Figure 2-26**). Between the two halves is a Data Bar, which presents a dedicated display of real-time winds and temperatures, as well as True Airspeed (TAS) and GPS Ground Speed (GS).

- 1 Attitude Display
- 2 Databar
- 3 Navigation Display

Unlike the mechanical indicators it typically replaces, EFD1000 PFD can also display all the data provided by the remaining four instruments in the “six pack” (airspeed, altitude, turn and slip, and vertical speed), as well as much more. Concentrating all primary flight information onto a single instrument directly in front of the pilot improves instrument scan and reduces pilot workload, thereby enhancing safety, especially in busy phases of flight. Additionally, analog backup primary instruments remain in the pilot’s primary field of view, and should be included in the instrument scan to cross-check indications of both the primary (EFIS) and backup (analog) instruments.

The EFD1000 PFD generally follows standard display conventions for Electronic Flight Instrument Systems (EFIS), so a pilot with some experience and familiarity with other EFIS PFDs will usually transition quickly to using the EFD1000. Pilots for whom the EFD1000 PFD is their first real exposure to EFIS and “glass cockpit” flying, however, should get some in-flight transition training from a certified instrument flight instructor (CFII) with EFIS experience. Pilots are also encouraged to study some of the excellent publications now available to help the transition from analog to EFIS instrument flying, including the FAA’s latest versions of the Instrument Flying Handbook.

This section gives an overview of the main display elements and features. For more detail, see the **Reference Guide, Chapter 4**.

### 2.3.1. Attitude Display

The Attitude Display includes an Attitude Director Indicator (ADI) with single-cue Flight Director command V-bars (when connected to a compatible autopilot), an Airspeed tape, an Altimeter tape, an Altitude Alerter (with separate minimums alerting), and Instrument Approach indicators (**Table 2-6 and Figure 2-27**). For more details on each, see the **Reference Guide, Chapter 4**.

The Airspeed and Altitude tapes are the most obvious differences from a mechanical ADI. These tapes are common on most EFIS PFDs, and will be immediately familiar to pilots with EFIS experience. Pilots without prior EFIS experience may need some time, experience, and training to get comfortable using the Airspeed and Altimeter tapes as their primary references.

In single-tube EFD1000 PFD installations, where the mechanical airspeed indicator and altimeter remain in their original locations, transitioning pilots can use either their familiar mechanical instruments or the PFD tapes for airspeed and altitude references. Many pilots new to EFIS quickly find themselves relying on the tapes within just a flight or two. If the tapes prove distracting at any time, however, the pilot can remove them from the display by pressing the TPS Hot Key (**Figure 2-2 No. 66**, single-tube installations only).



ATTITUDE DISPLAY	
16	Attitude Display/Attitude Director Indicator (ADI)
17	Aircraft Symbol
18	Single-Cue Flight Director (optional)
19	Roll Pointer
20	Slip/Skid Indicator
21	Altitude Tape
22	Selected Altitude Field
23	Altitude Alert
24	Altitude Drum/Pointer
25	Altitude Bug
26	Decision Height Annunciation
27	Selected Minimums Field
28	MINIMUMS annunciation
29	LDI Navigation Source Indication
30	Airspeed Indicator Tape
31	Selected Airspeed Field
32	Airspeed Bug
33	Airspeed Drum/Pointer
34	Vertical Deviation Indicator
35	Lateral Deviation Indicator

Table 2-6 Attitude Display Components

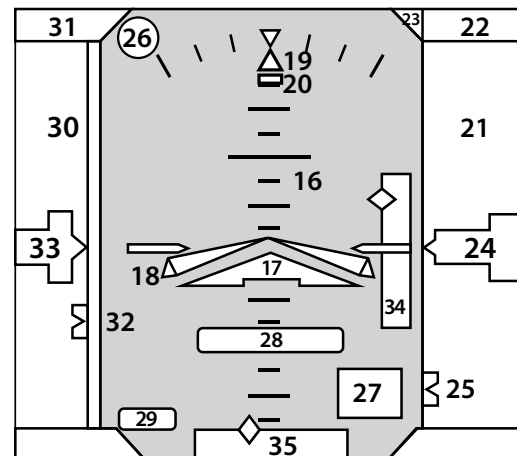
Figure 2-27  
Attitude Display Components



Figure 2-28  
Slip/Skid

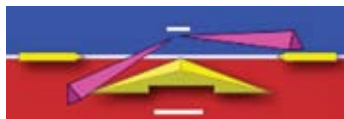


Figure 2-29  
Flight Director

### 2.3.1.1. Attitude Director Indicator (ADI)

The Attitude Director Indicator (ADI) features a conventional blue (sky) over brown (ground) background, with a white horizon line dividing the two areas. A triangular aircraft reference symbol (**Ref. 17**) is in a fixed position, and shows aircraft attitude relative to the horizon.

The pitch scale (or ladder) indicates degrees of nose up (blue) or nose down (brown) pitch relative to the apex of the aircraft symbol. Minor pitch marks are shown every 2.5° up to  $\pm 20^\circ$  of pitch, with major pitch marks every 10° up to  $\pm 90^\circ$  of pitch. The distance between pitch marks is greater than on most mechanical attitude indicators, making it easier for the pilot to fly more precise pitch attitudes.

At extreme pitch attitudes (above 30° nose up or below 25° nose down), red Unusual Attitude Recovery chevrons appear, pointing towards the horizon. At extreme pitch attitudes, some sky (blue) or ground (brown) will always be displayed to help maintain situational awareness, even though the horizon line may be off-scale.

At the top of the ADI are the roll scale, roll pointer, and slip/skid indicator (**Figure 2-28**). The roll scale is indicated by tick marks at 10°, 20°, 30°, 45°, and 60° on both sides of the zero roll inverted solid white triangle. The 45° marks are represented as hollow triangles.

Slip/skid is indicated by the lateral position of the white rectangle under the roll pointer. One rectangle width is equivalent to one ball width of a conventional inclinometer.

When connected to a compatible autopilot system the EFD1000 will display a single-cue Flight Director (**Figure 2-29**). The Flight Director command bars visually represent the lateral and vertical steering cues transmitted to the EFD by the autopilot. When the FD output from the autopilot is unavailable or flagged invalid, the FD command bars are removed from the display.

### 2.3.1.2. Airspeed Tape and Bug

Airspeed is indicated by a moving airspeed tape against a fixed position airspeed pointer, shown on the left-hand side of the Attitude Display (**Figure 2-30**). A digital, rolling drum readout indicating airspeed values to the closest one knot or mile per hour is provided adjacent to the fixed pointer. Tick marks are provided on the airspeed tape every 10 knots (or mph, if so configured). Airspeeds will be displayed between 20 kts (23mph) to 450 kts (518mph). Outside of this range the airspeed value is dashed.

Color speed bands are displayed on the indicated airspeed tape, corresponding to the colored arcs found on a traditional airspeed instrument.

Color speed markers are displayed on the indicated airspeed tape, corresponding to the colored radial lines found on traditional airspeed instruments. All aircraft have a red line for aircraft never-exceed speed ( $V_{ne}$ ). Multi-engine aircraft will usually also have a lower red line for single-engine minimum control speed ( $V_{mc}$ ), and a blue line for single-engine best rate of climb speed ( $V_{yse}$ ). If the aircraft manufacturer has published an initial flap extension speed, a white triangle will be presented on the airspeed tape at the speed corresponding to this limitation.

Textual V-speed markers can also be shown on the airspeed tape (e.g.,  $V_x$ ,  $V_y$ ,  $V_a$ , etc.). These are typically programmed at installation, and (if left unlocked during installation) may also be programmed by the pilot. V-speed display can be enabled or disabled by the pilot from Page 1 of the Main Menu (see **Chapter 5**).

The pilot can set a target airspeed using the left-hand control knob (see **Section 4.1.2.1**). The target airspeed is shown on the Airspeed Tape in the form of an Airspeed Bug (**Figure 2-2, No. 32**), and will also be displayed numerically above the Airspeed Tape (**Figure 2-2, No. 31**). The bug and numerical value are for visual reference only, to help the pilot maintain a target airspeed; there is no alerting for deviations from the target.

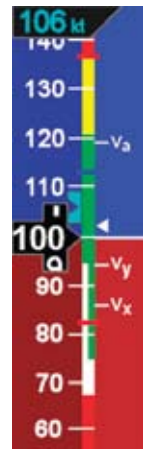


Figure 2-30  
Airspeed Tape



Figure 2-31  
Altitude Tape

### 2.3.1.3. Altitude Tape and Alerter

Altitude is indicated by a moving altitude tape against a fixed position altitude pointer (**Figure 2-2, No. 24**), shown on the right-hand side of the Attitude Display (**Figure 2-31**). A digital, rolling drum readout indicating altitude values to the closest 20 feet is provided adjacent to the fixed pointer. Minor tick marks are provided on the tape at 20-foot intervals, and major tick marks are provided at 100-foot intervals. The thousands and ten-thousands digits are larger than other digits on the tape. Negative altitudes are indicated by a “-” sign preceding the numerical altitude value in the drum.

The current altimeter barometric setting is shown just below the Altitude tape in the Data Bar (**Figure 2-2, No. 37**), and can be adjusted using the Right Knob.

The Altitude Tape also includes a built-in altitude alerter, which consists of an Altitude Bug on the Altitude Tape (**Figure 2-2, No. 25**), a Selected Altitude display (**Figure 2-2, No. 22**), a visual Altitude Alert (**Figure 2-2, No. 23**), and optionally, an audio alert. For more information on using the Alerter see **Chapter 3** and **Chapter 4**.

The Vertical Speed Indicator (VSI) is shown on the Navigation Display (**Figure 2-31 and Figure 2-2, No. 55**), to the right of the HSI.

### 2.3.1.4. Instrument Approach Indicators

Additional indicators are shown or available on the Attitude Display when flying certain types of instrument approaches. These enable the pilot to maintain a tighter instrument scan on the ADI, reducing workload and improving safety (**Figure 2-32**).

A Lateral Deviation Indicator (LDI, (**Figure 2-2, No. 35**)) is presented on the attitude indicator whenever the pilot has coupled an ILS, LOC, LOC(BC), or a GPS in Approach Mode to the HSI, and valid lateral guidance is being provided. The navigation source coupled to the LDI is annunciated to the left of the LDI (**Figure 2-2, No. 29**).

A Vertical Deviation Indicator (VDI, (**Figure 2-2, No. 34**)) is presented on the attitude indicator whenever the LDI is shown and valid vertical guidance is provided, such as from an ILS or WAAS GPS.

Whenever the lateral or vertical deviation exceeds the maximum displayable range of 2.5 dots, the deviation diamond is rendered as a hollow, ghosted image pegged to the corresponding side. As soon as the deviation comes into range, the diamond turns solid green, making it easy to identify when the needle is alive.

Additionally, the pilot can pre-set the minimums (MIN) for the approach, which will be displayed on the ADI (**Figure 2-2, No. 28**) until the pilot toggles off the display using the MIN hot key. Once the MIN data field value is set to a Decision Altitude or Minimum Descent Altitude, the EFD1000 PFD provides an alert when the aircraft reaches or descends below this altitude.

If a Radar Altimeter is installed in the aircraft and connected to the EFD1000, a Decision Height annunciation (**Figure 2-2, No. 26**) will be displayed when the aircraft descends to or below the selected radar altitude (**Figure 2-33**).



Figure 2-32  
Instrument Approach Indications



Figure 2-33  
Decision Height Annunciation

**NOTE**

*When the winds aloft are less than 10 knots, the wind data is dashed.*

36				37
41	40	39	38	

Figure 2-34  
Databar Components

### 2.3.2. Data Bar

The Data Bar visually separates the upper and lower halves of the PFD display. When available, True Airspeed (TAS), GPS Ground Speed (GS), Outside Air Temperature (OAT), Wind Vector arrow, Wind Direction and Speed, and Barometric Pressure Setting data are presented in the data bar (**Table 2-7** and **Figure 2-34**).

When any of these values is unavailable or invalid, the corresponding data field is dashed. A GPS navigator must be connected and providing valid ground speed and track data to display GS and winds aloft data.

The Data Bar is discussed in detail in **Section 4.2**.

DATABAR	
36	True Airspeed
37	Barometric Pressure Setting Field
38	Wind Direction and Speed
39	Wind Direction Arrow
40	Outside Air Temperature
41	Ground Speed

Table 2-7 Databar Components

### 2.3.3. Navigation Display

The lower half of the EFD1000 PFD is the Navigation Display, which shows a wide range of navigation information and flight data, including **(Figure 2-35)**:

- Horizontal Situation Indicator (HSI), with Course Pointer and Deviation Indicator (CDI), and Heading Bug, offering both 360° and ARC mode views.
- Digital readouts of current magnetic heading, selected heading (HDG), and selected course (CRS).
- Information about the currently selected navigation source, or active GPS waypoint.
- Ground Track indicator.
- Vertical Speed Indicator (VSI) tape and digital rate value.
- Rate of Turn indicator.
- Dual bearing pointers (RMI).
- Situational awareness Map display.
- Identification of the navigation sources to which the Course Deviation Indicator (CDI) and two bearing pointers are currently coupled.
- GPS Annunciations (TERM, APPR, WPT and MSG).
- Caution annunciations for abnormal GPS status.

When connected to a GPS navigator, basic mapping can also be displayed under the HSI display, including GPS flight plan legs and waypoints, and (when connected to a compatible GPS) nearby navigation data (airports, VORs, NDBs and intersections).



#### NOTE

*The Vertical Deviation Indicator (VDI) and Lateral Deviation Indicator (LDI) are part of the navigation instruments but display on the Attitude Display.*

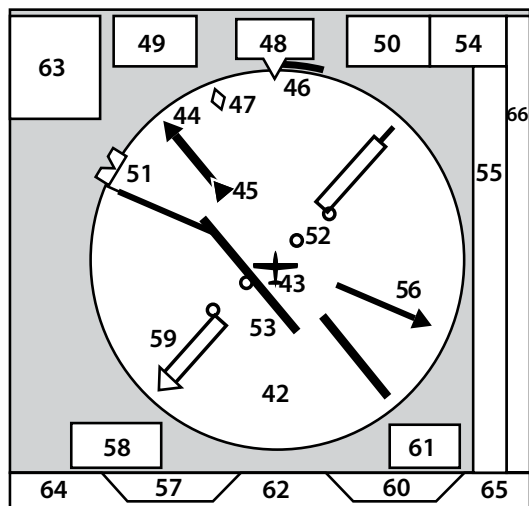


Figure 2-35  
Navigation Display Components

#### NAVIGATION DISPLAY

42	Navigation Display	55	Vertical Speed Tape
43	Owship Symbol	56	Single-Line Bearing Pointer
44	Course Pointer	57	Single-Line Bearing Pointer Source
45	TO/FROM Indicator	58	Single-Line Source Info Block
46	Rate of Turn Indicator	59	Double-Line Bearing Pointer
47	Track Marker	60	Double-Line Bearing Pointer Source
48	Magnetic Heading	61	Double-Line Source Info Block
49	Selected Course (CRS) Field	62	CDI Navigation Source
50	Selected Heading Field	63	CDI Source Information Block
51	Heading Bug	64	Left Control Knob State
52	Course Deviation Scale	65	Right Control Knob State
53	Course Deviation Indicator	66	Hot Key Legend
54	Vertical Speed Digital Value		

Table 2-8 Navigation Display Components



### 2.3.3.1. Horizontal Situation Indicator (HSI)

The traditional HSI is an instrument that combines a slaved magnetic Heading Indicator overlaid with a rotating Course Pointer and Deviation Indicator (CDI). This combination has also been called a pictorial navigation indicator, because it helps the pilot better visualize the aircraft position relative to its desired course. The HSI is a vast improvement over the older, separate Directional Gyro (DG) and OBS course deviation indicator, because the compass heading is always correct (slaved to a remote magnetic flux detector), and integration of the CDI onto the compass simplifies the instrument scan and provides better situational awareness.

Pilots experienced with mechanical HSIs will find the 360° mode of the EFD1000 Navigation Display immediately familiar. In its basic form, it is just an electronic representation of a mechanical HSI. Pilots transitioning from flying a DG and OBS should get some dual instruction from a CFII on the differences in flying an HSI, because some instrument flying techniques differ from what they may be used to.

#### **Compass Modes: 360° vs. ARC**

The HSI on the EFD1000 can be presented in either a full 360° compass rose mode (shown in Figure 2-35), or in a 100° ARC format (Figure 2-36). In 360 Mode, the HSI resembles the mechanical instrument, with the ownship position in the center of the display. ARC Mode provides an extended forward view with the ownship position at the bottom of the display. The ARC mode is especially good for map displays. The middle Hot Key is used to toggle the display between 360 and ARC modes, with the current mode shown in green adjacent to the Hot Key.



Figure 2-36  
ARC CDI Mode with Base Map



Figure 2-37  
Magnetic Heading



Figure 2-38  
Navigation Source Information Block

### ***Navigation Setting Information***

Regardless of compass mode setting, the current magnetic heading is always shown at the top center of the Navigation Display (**Figure 2-2, No. 48 and Figure 2-37**). The current setting of the HDG Bug is shown in the Selected Heading Field (**Figure 2-2, No. 50**), which is to the right of the ship's Magnetic Heading (**Figure 2-2, No. 48**). This field is always visible even if the HDG Bug itself is not visible in ARC mode. Similarly, the current Course setting (CRS) (**Figure 2-2, No. 49**) is always shown to the left of the ship's heading, whether or not the Course Pointer itself is visible in ARC mode.

A Navigation Source Information Block (**Figure 2-2, No. 63 and Figure 2-38**) is presented in the upper left corner of the HSI display area. The Source Information Block indicates the navigation source coupled to the CDI and its associated mode (e.g. VOR, ILS, LOC, etc). Information is provided related to the coupled source, including, when available, waypoint or navaid identifier or frequency, bearing and distance, and the estimated time to the active waypoint.

### ***Course Pointer and Deviation Indicator (CDI)***

In the 360° compass mode, the Course Pointer and Deviation Indicator (CDI) resemble those of a mechanical HSI, with an arrowhead pointing to the selected course, and a movable center section indicating course deviation against a scale of two dots to either side of the center. A TO/FROM indication is shown as a triangle above (TO) or below (FROM) the end of the deviation bar.

Within the ARC mode, the pilot may select (via the Main Menu) between two different formats of CDI presentation – ARC HSI mode and ARC CDI mode. The ARC HSI mode, presents a full rotating Course Pointer with CDI, which resembles that used in the HSI 360 Compass mode. The ARC CDI mode presents a short Course Pointer stub on

the compass arc, and a fixed CDI at the bottom of the display, similar to the LDI and resembling that used in contemporary GPS navigation displays. ARC CDI mode leaves more open space for map presentation. A TO indication is shown to the left of the LDI, while a FROM indication is shown to its right.

### **Deviation Off Scale Indication**

Whenever the course deviation exceeds the maximum displayable range of 2.5 dots, the CDI bar or deviation diamond is rendered as a hollow, ghosted image pegged to the corresponding side (**Figures 2-39 and 2-40**). As soon as the deviation comes into range, the CDI or diamond turns solid green, making it easy to identify when the needle is alive.

### **Auto Course Select**

When a GPS is selected as the CDI navigation source, the default setting of the EFD1000 is "Auto Course Select", in which mode the GPS will automatically set the Course Pointer to the current GPS course (CRS) value whenever the GPS sequences between waypoints. This capability relieves the pilot from manually setting the course at each waypoint transition along a GPS route. When Auto Course Select is active, the pilot cannot adjust the CRS value.

Auto Course Select is indicated by an "A" on a green background, adjacent to both the numerical CRS value and the "CRS" knob legend (**Figures 2-41 and 2-42**).

If the GPS navigator enters OBS, HOLD, or SUSPEND modes, Auto Course Select is automatically disabled on the EFD1000 until the GPS resumes waypoint sequencing. The pilot can also manually disable Auto Course Select from Page 1 of the Main Menu.



Figure 2-40  
Off Scale ARC CDI



Figure 2-39  
Off Scale CDI



Figure 2-42  
Auto Course Indication on  
Left Control Knob State



Figure 2-41  
Auto Course Indication on  
CRS Field



Figure 2-43  
Current Heading



Figure 2-44  
Rate of Turn Indicator, Rate Shown >6°/second

### Ground Track Indicator

Whenever the EFD1000 is connected to a compatible GPS, a Ground Track Indicator is displayed. Ground Track is shown as a blue diamond rendered on the compass scale at the value that corresponds to the current aircraft track (**Figure 2-2, No. 47 and Figure 2-43**).

When the blue track diamond is aligned with the Course Pointer, the aircraft is tracking on or parallel to its desired track. To align the track diamond with the Course Pointer, turn away from the direction in which the diamond is offset from the Course Pointer (think of it as “pulling” the track diamond toward the Course Pointer).

#### 2.3.3.2. Rate of Turn Indicator

A rate of turn indicator (**Figure 2-2, No. 46**) with a range of 0 to 6 degrees per second is provided for both the 360 and ARC Compass modes. The indicator consists of a curved white tape originating from the heading index mark and extending in the direction of the turn along the outer curve of the compass card.

The rate of turn indicator features an outer thick white tick mark for a Standard Rate turn, and an inner thin white tick mark for Half-Standard Rate turns. A Standard Rate, two-minute turn equals 3 degrees per second. When the rate of turn exceeds 6 degrees per second, an arrowhead is added to the end of the tape to show that the rate of turn has exceeded the limits of the indicator (**Figure 2-44**).

### 2.3.3.3. Vertical Speed Indicator (VSI)

Whenever the vertical speed exceeds +/- 100 FPM, the vertical speed is indicated by presenting a rising/sinking white vertical tape and associated scale markers immediately to the right of the compass rose (**Figure 2-2, No. 55 and Figure 2-45**).

A numerical indication of current aircraft vertical speed is shown directly above the tape (**Figure 2-2, No. 54**). Rates of up to  $\pm 2000$  feet per minute (FPM) are indicated by the tape, while the numerical value will display rates of up to  $\pm 9990$  FPM. A triangle caps the tape whenever rates exceed  $\pm 2000$  FPM (**Figure 2-46**). The vertical speed data field will be “dashed” whenever the vertical speed is 10,000 FPM or greater.

In the ARC compass mode, only the digital vertical speed value is presented.

### 2.3.3.4. Bearing Pointers

One or two bearing pointers that show the bearing to a VOR station or GPS waypoint can be overlaid on the HSI (**Figure 2-47**). BRG#1 is a single needle (**Figure 2-2, No. 56**), and BRG#2 is the double needle (**Figure 2-2, No. 59**). Use the Nav Source Select Buttons (**Figure 2-2, No. 10 and No. 12**) to select the nav source for a Bearing Pointer, or select none (blank) to remove the Bearing Pointer from the display.

The head of the needle always points to the station or waypoint. When coupled to a VOR source, the tail of the needle indicates the VOR radial on which the aircraft is currently located. Bearing pointers are excellent tools for identifying crossing radials, flying DME arcs, and for general situational awareness.

Bearing Pointers are only available in the 360 Compass mode. Any available navigation source may be coupled to either bearing pointer. If coupled to a source that does not provide angular bearing data, such as a localizer, the bearing pointer is not presented and the source is flagged as invalid.

Each bearing pointer has an associated source information block that can display

Figure 2-46  
VSI Tape Capped, Digital Value  
Showing 2,100 FPM Climb



Figure 2-45  
VSI Tape Showing  
300 FPM Descent



Figure 2-47  
BRG#1 Set to VOR1 on 117.9;  
BRG#2 Set to GPS2, SWR

information about the source of the bearing pointer data. Information that can be displayed includes distance to station (if coupled to a GPS waypoint) and either the station identifier or the tuned frequency for a VLOC radio. This information is only presented when it is reported to the EFD1000 by the connected equipment, and thus is not available in all installations.

### 2.3.3.5. Situational Awareness Map Display

When the EFD1000 is connected to a compatible GPS navigator, a base map can be displayed underneath the HSI in either 360° or ARC modes. Most GPS put out data to enable the EFD1000 to display the active GPS flight plan legs and waypoints. The active GPS flight plan leg, waypoint, and its identifier are shown in magenta. Other waypoints and legs are shown in white.

Some GPS navigators (typically those using the ARINC 429 data protocol, such as the Garmin 400/500 series) additionally put out information on nearby nav data waypoints (e.g., airports, VORs, NDBs and intersections), which can also be displayed on the EFD1000 base map. These GPS can often also display curved flight paths, such as course reversals and holding patterns.

The base map is always oriented with magnetic heading up and centered so that the current aircraft position coincides with the aircraft ownship symbol. These base map elements underlay all other instruments and annunciations in the Navigation Display.

The MAP hot key is used to cycle through four levels of map features display and to

turn off the base map display. Each successive press of the MAP hot key selects the next feature level or OFF.

The map display range is controlled by the Range Control toggle button (**Figure 2-2, Ref. 2**), enabling the pilot to zoom in or out on the map. Automatic declutter logic changes the map features display depending on the selected map range.

The current map settings (range and feature level) are shown in the lower left-hand corner of the navigation display whenever the map is not OFF (**Figure 2-48**). The current map range is displayed in nautical miles, measuring the distance from the ownship symbol to the edge of the map display. The current map feature level is indicated by one to four green trapezoids underneath the range value (one mark is flight plan-only, while four marks is the highest map feature level).



Figure 2-48  
Map in ARC Mode, 20nm Range at  
Feature Level 3 (Medium)





## Chapter 3

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### Flying the EFD1000 Pro PFD

This chapter provides an overview of flying the EFD1000 Pro PFD on an IFR cross-country flight, explaining how to access and change the necessary settings of the EFD1000 PFD (**Table 3-1**). Refer to **Chapter 4** for detailed step-by-step instructions for all EFD1000 PFD functionality.

While you can jump right into using the EFD1000 Pro PFD with this chapter, it may be helpful first to read **Chapter 2** to become more familiar with the controls, operating logic, and display elements of the PFD.

The EFD1000 Pro PFD is a powerful Electronic Flight Instrument System (EFIS), offering the same capabilities and features found on larger glass cockpit systems in airliners, business jets, and newer general aviation aircraft. It is capable of far more than the analog instruments it typically replaces. It will take some time and experience to master all of its advanced capabilities, especially if this is your first exposure to flying EFIS and glass cockpits. Nonetheless, in its most basic configuration, the EFD1000 PFD will look immediately familiar to anyone used to flying mechanical instruments, and its basic operation is very similar and intuitive .

Before flying your new EFD1000 installation on an actual IFR flight, be sure first to spend some time with your installer to understand exactly how your aircraft is configured, and also to get some dual instruction and practice time in VFR conditions until you are comfortable with how the EFD1000 performs and integrates with the other avionics in your airplane.

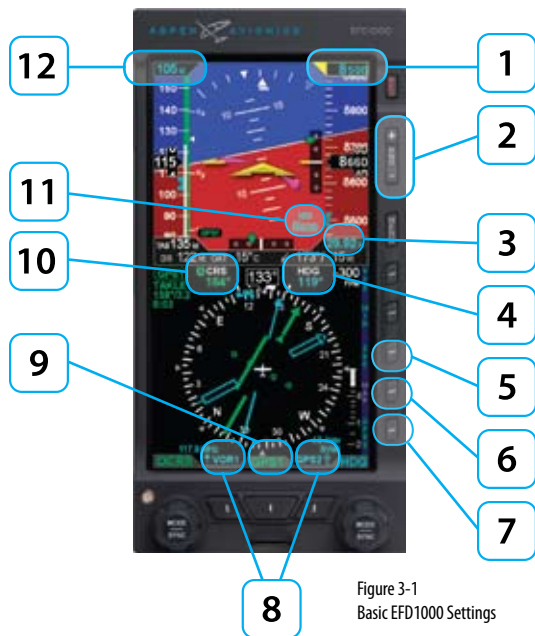


Figure 3-1  
Basic EFD1000 Settings

FEATURE		SETTING	FEATURE		SETTING
1	Selected Altitude	Set as desired	7	GPS Steering (GPSS) Hot Key	Enable/Disable
2	Map Range Keys	Set as desired	8	Bearing Pointers Nav Source	Select as desired
3	Barometric Pressure Setting	Check and set	9	CDI Navigation Source	Select as desired
4	Heading Bug Value	Set as desired	10	Course Pointer Value	Set as desired
5	Compass Mode, 360° or ARC	Set as desired	11	MINIMUMS Setting	Set approach minimums
6	Map Settings Hot Key	Set as desired	12	Selected Airspeed	Set as desired

Table 3-1 Basic EFD1000 Settings

## 3.1. Quick Controls Overview

**Chapter 2** explains the EFD1000 controls in detail. The following is a quick summary:

### Control Knobs (see 2.2.1 for detail)

- The Left and Right control knobs each has a Home state, to which it returns after 10 seconds of inactivity. The left knob is the CRS knob, and the right knob is the HDG knob.
- The current function of each knob is shown by a legend on the screen immediately above the knob. If the legend is shown in magenta, turning the knob will change the value of the function shown. If the legend is shown in cyan or green, turning the knob will have no effect.
- From the Home state, pressing the knob once will enable the current function to be set (legend color changes from cyan to magenta). Successive presses of the knob will cycle through the functions that knob can control. When the function you want to change is shown in magenta, turning the knob will change the value.
- The Left control knob sets the Course Pointer (CRS, except when Auto Course Select is enabled) and Indicated Airspeed Bug (IAS).
- The Right control knob sets Heading (HDG), Selected Altitude (ALT), Barometric Pressure Setting (BARO), and Approach Minimums (MIN).
- Pressing and holding a knob syncs the function shown to the current value.

**NOTE**

*The tasks and procedures you will use in your airplane will vary depending on your aircraft and equipment, and on how they are configured and integrated with the EFD1000 in your specific installation.*

### **Navigation Source Buttons (see 2.2.2 for detail)**

- Three buttons at the bottom of the display couple the available navigation sources to the CDI and/or the bearing pointers.
- The center button (**Figure 2-2, Ref. 11**) selects the nav source to couple to the CDI and to drive the autopilot (if installed).
- The outer two buttons (**Figure 2-2, Refs. 10 and 12**) select which nav source couples to each of the two bearing pointers (or none to hide the bearing pointers).

### **Hot Keys (see 2.2.3 for details)**

- The five buttons on the lower right-hand side of the display are Hot Keys, the function of which is shown by the legend on the screen immediately adjacent to each button.
- The current status of each Hot Key is shown by the legend, in GREEN if active and in GRAY if inactive.
- Each press of a Hot Key will either toggle its function on or off, or will cycle among available settings.

## **3.2. Example Flight Scenario**

This section will walk you through using the EFD1000 Pro PFD on an IFR flight from Albuquerque International Sunport (KABQ) to Reno/Tahoe International Airport (KRNO), flying Victor airways to the ILS16R approach into KRNO. This scenario uses one pilot's technique for setting up the navigation instruments, but there are many other valid possibilities. Use whatever techniques work best for you.

Our aircraft for this flight is a Beech Bonanza A36TC, equipped with dual Garmin GNS-430W WAAS GPS/nav/comms and the Bendix/King KFC-200 autopilot. The EFD1000 Pro

PFD is configured with Auto Course Select enabled, baro setting in inches, V-speed text markers displayed, ARC compass mode in CDI, and the base map configured with its default settings.

The Garmin 430Ws are configured with ILS CDI Capture set to AUTO, meaning that when an ILS approach is loaded and active in the GPS, and the aircraft is established inbound to the FAF, the 430W will automatically switch its CDI output from GPS to the VHF localizer frequency. The EFD1000 will follow this switch on its CDI Source Select, automatically changing from GPS1 to VLOC1.

### 3.2.1. Pre-Departure (Startup)

Once the pre-flight inspections and checklists are complete, and before starting engines, turn the Battery Master ON.

When power is applied to the EFD1000, the bezel backlighting illuminates and the EFD1000 PFD splash screen displays while the EFD1000 PFD initializes (**Figure 3-2**).

As the software initializes and the PFD warms up, the Attitude and Navigation Displays will appear first (typically within 20-30 seconds), with red X's showing for the airspeed and altitude tapes (**Figure 3-3**). In a short while (from a few more seconds to a few minutes, depending on how cold the aircraft is), the air data sensors will warm up to operating temperature and the airspeed and altitude tapes will appear. At that point, the EFD1000 is ready to go. The PFD will usually be ready by the time engines are started or the After Start checklist is complete.



Figure 3-2  
EFD1000 PFD Initializing

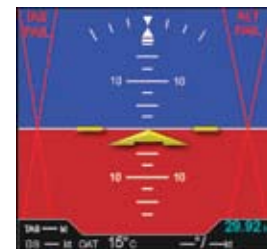


Figure 3-3  
Initialization Complete,  
Sensors Warming Up



Figure 3-4  
CDI Source Slashed Invalid



Figure 3-6  
GPS2 Shown Flagged



## NOTE

*Whenever there is a new altimeter setting, be certain to set both the EFD1000 PFD and the mechanical standby altimeter.*



## NOTE

*Start-up times for the EFD1000 are highly dependent on aircraft temperature. In extremely cold weather, when the aircraft has gotten cold soaked overnight, it may take several minutes (usually no more than five) for the PFD to be fully operational. On the second or third flight of the day, and/or on very hot days, the PFD may come up within 30 seconds or less.*

After engine start, turn the Avionics Master ON. Until the navigation radios are operational, the nav source annunciations on the EFD1000 will be shown with a red line slashed through them (**Figure 3-4**), and the GPS1, GPS2 and INTEG cautions will be annunciated on the left edge of the display (**Figure 3-5 and 3-6**). The CDI Source Select will default to VLOC1. Once the nav radios have warmed up, the red slash will be removed from the CDI Source annunciation.



## NOTE

*GPS will not output valid navigation information until programmed with an active flight plan or direct-to waypoint, and thus will be flagged on the EFD1000 and cannot be selected as a CDI or Bearing Pointer navigation source until they are programmed with an active waypoint.*

Once the radios are available, we pick up the ATIS, and learn that the local altimeter setting is 30.15, and that Runway 8 is in use for departures.

First set the standby altimeter to 30.15, and then set the EFD1000 PFD baro setting.

When the EFD1000 is interfaced to a Garmin 4xx/5xx or 4xx(W)/5xx(W) navigator, and the navigator's Instrument Panel Self-Test page is displayed, the indicated lateral deviation can be verified on the EFD1000 HSI. This confirms that a valid digital signal was received from the Garmin system.

The interface between the Garmin 4xx/5xx and EFD1000 system should be considered fully operational once the presence of the digital signal is confirmed. If there is no GPS failure annunciation on the EFD1000, the deviation indicator flags are not asserted, and the lateral deviation indication on the EFD1000 HSI correlates to the indication on the Garmin 4xx/5xx Instrument Panel Self-Test Page, then the digital signal is confirmed and the interface is operational.

The navigator's indicated lateral and vertical deviation cannot be compared to the EFD1000's Lateral Deviation Indicator (LDI) and Vertical Deviation Indicator (VDI) because the 4xx/5xx Instrument Panel Self-Test Page does not output an Approach Mode assertion.

Due to safety and certification issues, the display of the LDI and VDI without an Approach Mode assertion is not permitted on an EFD1000 system.

The display of deviations on the LDI and VDI are not necessary to verify the communication between the Garmin 4xx/5xx and EFD1000 system.

### Set the Barometric Pressure

1. Press the Right Knob until BARO displays above the knob and the Barometric Pressure field is enabled for editing, both rendered in magenta (**Figure 3-7**). From the Home state, press the Right Knob 3 times to enable setting baro pressure.
2. Rotate the Right Knob to change the value of the Barometric Pressure field. Rotate clockwise to increase, or counterclockwise to decrease, the value. Once the correct value is selected and after 10 seconds of inaction, the field is disabled and the label and field are rendered in cyan (**Figure 3-8**).

Figure 3-7  
BARO Field Enabled



Figure 3-8  
BARO Field Disabled



### **NOTE**

*The graphics used in this chapter illustrate the features and tasks being described, but do not necessarily correspond to the values associated with this example flight scenario.*



Figure 3-9  
Heading Field Enabled



Figure 3-10  
Heading Field Disabled

Next, since we'll be departing from Runway 8, we set our Heading Bug to runway heading, 080°.

### Set the Heading Bug

1. Press the Right Knob until HDG displays above the knob and the HDG field is enabled for editing, both rendered in magenta (**Figure 3-9**). The Heading Bug will also be rendered in magenta, and a dashed magenta line will extend from the ownship symbol to the Heading Bug to make it easier to see the bug position.
2. Rotate the Right Knob to change the value of the Heading field. Rotate clockwise to increase, or counterclockwise to decrease, the value. Once the correct heading is selected and after 10 seconds of inaction, the field is disabled and the label and field are rendered in cyan (**Figure 3-10**).

We call Clearance Delivery to pick up our IFR clearance. It is:

*"Bonanza N66529 is cleared to the Reno/Tahoe Airport via the LARGO2 departure, Zuni (ZUN) transition, then as filed. Maintain 7,000, expect 10,000 in five minutes. Departure frequency is 127.4. Squawk 1234."*

Now we set up our avionics for an instrument departure. We set our transponder code and comm radio frequencies. Then we enter our flight plan into GPS1, load the LARGO2 departure, crossfill into GPS2, and activate the flight plan.

The LARGO2 departure calls for vectors to our route. From past experience, we expect to be vectored past ABQ VOR, and then given a vector to join the departure on the ABQ-to-ZUN leg (a 255° course). While we'll be navigating on GPS, for situational awareness we tune those first two VOR fixes into our nav radios. We tune ABQ VOR (113.2) into VLOC1 and ZUN VOR (113.4) into VLOC2.



On the EFD1000, use the CDI Source Select button to select GPS1. Because we have enabled Auto Course Select, the Course Pointer automatically slews to 261° (the initial course from the airport to the first fix on the LARGO2 departure, ABQ VOR).

### Select The CDI Navigation Source

- Press the CDI Navigation Source Select button (**Figure 3-11**) until the desired navigation source is shown above the button (e.g. GPS1, GPS2, VLOC1, VLOC2).

For a traditional RMI view, we could use our two Bearing Pointers to monitor our passing ABQ VOR and then intercepting the course to ZUN. We'd use the left BRG#1 Bearing Pointer Source Select button to select VOR1 (ABQ), and use the right BRG#2 Bearing Pointer Source Select button to select VOR2 (ZUN).

### Select Bearing Pointer Nav Sources

- Press the BRG#1 (single-line) or BRG#2 (double-line) Bearing Pointer button until the desired navigation source is shown above the button (**Figure 3-12**).



Figure 3-11  
CDI Navigation Source Selection Button



Figure 3-12  
Bearing Pointer Nav Source Select Buttons



### NOTE

When no source is selected, only the bearing pointer icon displays above the applicable button (**Figure 3-13**).



Figure 3-13 No Bearing Pointer Sources Selected

**NOTE**

The icons and flight plan legs rendered for each of the map display levels (High, Medium, and Low) are based on the selected map range. Detailed information is provided, in **Section 5.2** of this guide. In addition, some of the icons can be manually reconfigured, as discussed in that same section.

For even better situational awareness, we choose to display the map of our flight plan legs and waypoints. We press the MAP Hot Key to bring up the base map. We use the Range Control buttons to select the 20 NM. range, which will give a good perspective for intercepting our course to ZUN. Our initial flight plan leg, from the airport to ABQ VOR is shown in magenta, with subsequent legs and waypoints shown in white.

### Select Map Level of Detail

- Push the MAP Hot Key (fourth hot key) to cycle through and select the desired level of detail. Each time the hot key is pressed, the Map Declutter level icon changes to the next option (**Figure 3-14**).



Figure 3-14  
Changing the Map  
Display Level

### Change The Map Range

- Press the Range key (**Figure 3-15**) UP (+) to increase the range, or DOWN (-) to decrease the range, until the desired range is reached (**Figures 3-16 and 3-17**).

Figure 3-15  
Range Key



Figure 3-17

Current Range 10NM from  
Ownship to Edge of Compass



Current Range



Ownship  
Symbol

Figure 3-16

Current Range 200NM from  
Ownship to Edge of Compass

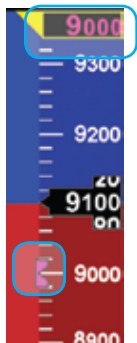


Figure 3-18  
Altitude Bug Enabled

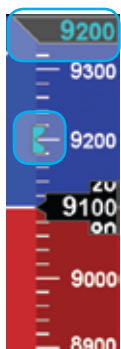


Figure 3-20  
Altitude Bug Disabled



Figure 3-19  
Altitude Field Enabled



## NOTE

*Setting the Altitude Alerter provides visual and aural cues to help the pilot capture and maintain target altitudes. When set to a new altitude, the Alerter will illuminate a yellow flag adjacent to the target altitude display, and sound a one-second tone, 15 seconds (or 200 feet) before the aircraft will reach the target altitude (based on current rate of climb or descent). The yellow flag will go black upon attaining the target altitude. Subsequently, if the aircraft deviates more than 200 feet above or below the target altitude, the flag will again illuminate and another one-second tone will sound to alert the pilot to the deviation.*

## Set the Altitude Alerter

1. Press the Right Knob until ALT displays above the Right Knob and the Altitude numerical field and bug are enabled for editing, all three rendered in magenta (**Figures 3-18 and 3-19**).
2. Rotate the Right Knob to change the value of the Altitude field. Rotate clockwise to increase, or counterclockwise to decrease, the value. Once the correct value is selected and after 10 seconds of inaction, the field is disabled and the label, numerical field, and bug are rendered in cyan (**Figure 3-20**).



## NOTE

*Synchronizing the altitude sets the selected altitude to the current altitude, see **Section 2.2.1.3**.*



## NOTE

*Synchronizing the altitude sets the selected altitude to the current altitude, see **Section 2.2.1.3**.*

Our normal climb speed is 120 KIAS, so we choose to set the airspeed bug as a reminder. To do so, we press the Left Control Knob twice, until it shows IAS in magenta above the knob. We turn the knob until 120 shows in the Selected Airspeed Field.

### Set the Airspeed Bug

1. Press the Left Knob until IAS displays above the Left Knob and the Selected Airspeed field and bug are enabled for editing, all three rendered in magenta (**Figures 3-21 and 3-22**).
2. Rotate the Left Knob to change the value of the Selected Airspeed field. Rotate clockwise to increase, or counterclockwise to decrease, the value. Once the correct value is selected and after 10 seconds of inaction, the field is disabled and the label and field are rendered in cyan (**Figure 3-23**).



Figure 3-22  
Selected Airspeed Bug Enabled



Figure 3-23  
Selected Airspeed Field Disabled



Figure 3-21  
Selected Airspeed Field Enabled



### NOTE

*Synchronizing the airspeed sets the selected airspeed to the current airspeed, see **Section 4.1.2.2**.*

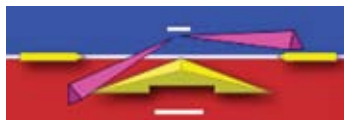


Figure 3-24  
Flight Director V-bars

We plan to hand-fly the plane until reaching our final en route altitude of 10,000 feet. But we like the help the Flight Director gives us (**Figure 3-24**). So, as part of our Before Takeoff set-up, we press the FD button on the autopilot mode selector, and the magenta V-bars display on the EFD1000. As an easy way to give us guidance on the takeoff, we press the Go Around button. This commands wings level and about a 10° pitch-up attitude, which works well for our initial climb.

Now our avionics are all set, so we taxi out to the runway, do our run-up, and call tower, ready for departure. As we taxi into position and hold on Runway 8, we verify that our EFD1000 compass shows 080°, lined up with our pre-set heading bug. As tower clears us for takeoff, it tells us to wait until reaching the end of the runway, and then to turn left to heading 250°. We press the Right Control Knob once to activate HDG, and turn the knob left to set the Heading Bug to 250.

### 3.2.2. Departure

As we start the takeoff roll, we note the airspeed on the EFD1000 comes alive at 20 KIAS. All indications are normal, so we continue the takeoff, rotate at 80 KIAS and fly the Flight Director command bars at 10° pitch up with wings level. As we run out of usable runway to land, we bring the gear up, and soon we're over the end of the 13,800 foot runway.

We engage HDG mode on the autopilot mode selector, and the FD commands a left turn to our assigned 250° heading, which we already set with the Heading Bug. We adjust our pitch attitude to maintain our target 120 KIAS climb speed as shown by the bug on our airspeed tape, and sync the FD pitch to that attitude.



Figure 3-25  
Altitude Alerter Flag Illuminated

Soon we hear a one-second tone and see the yellow flag come on next to our Selected Altitude at the top of the EFD1000 airspeed tape (**Figure 3-25**). This means we are 15 seconds away from reaching our assigned altitude. We begin to shallow our climb, and level off at 7,000 feet, engaging ALT hold on the AP/FD mode selector. The yellow Altitude Alert on the EFD1000 goes out as we capture and hold our altitude.

Around this time, on our 250° vector, we pass abeam ABQ VOR, which causes the GPS to sequence to the next flight plan leg to ZUN VOR. The Course Pointer on the EFD1000 automatically swings left to the new course, 255°, and that leg on our base map turns magenta.

Albuquerque Departure now tells us to fly heading 220° to join the LARGO2 departure, and climb and maintain 10,000.

1. Press the Right Knob once to activate HDG, and turn it left to set the Heading Bug to 220°.
2. Press the Right Knob again to activate ALT, and turn it right to set 10,000 in the Selected Altitude field at the top of the airspeed tape.

Auto Course Select has already set our Course Pointer to the 255° course from ABQ to ZUN on the LARGO2 departure, and a 220° heading sets us up for a nice intercept. We disengage ALT hold on the Flight Director, set our cruise climb attitude, sync the V-bars to that pitch, and initiate the climb from 7,000 to 10,000 feet, maintaining our target airspeed of 120 KIAS by reference to the Airspeed Bug (**Figure 3-26**).

At about 9,700 feet, the Altitude Alerter tone sounds, and the yellow alert flag by the Selected Altitude illuminates, telling us we are 15 seconds from reaching our assigned 10,000 feet. We begin our level-off, and upon reaching 10,000 feet, engage ALT hold on the FD mode selector.

Departure calls again to hand us off to Albuquerque Center on 133.0. As we're tuning the radio, we hear an alert tone. A glance at the EFD1000 shows the Altitude Alerter



Figure 3-26  
CDI Shown Hollow at Full-Scale Deflection



Figure 3-27  
CDI Alive and Shown Solid

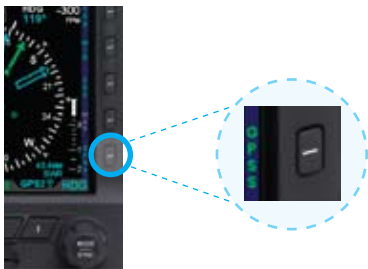


Figure 3-28  
GPSS Enabled (Legend in Green)

flag flashing, our altitude at 10,200 and climbing, and our Flight Director V-bars commanding pitch down. We quickly stop the climb, correct back down to our assigned altitude of 10,000 and engage the autopilot before calling to check in with Center.

### 3.2.3. En Route

Albuquerque Center gives us a new altimeter setting of 30.11. We set 30.11 on the standby mechanical altimeter, and then on the EFD1000.

- Press the Right Knob three times to select BARO, shown in magenta above the knob, and turn the knob left four clicks to set 30.11 on the meter.

Soon, the CDI comes alive and attracts our attention as it changes from hollowed out to solid and begins to move in towards the Course Pointer as we intercept our course. We enable GPS Steering to complete the intercept and steer us along the airways all the way to Reno (**Figure 3-27**).

1. Confirm the AP/FD mode selector is still in HDG mode.
2. Press the GPSS Hot Key, and verify its legend turns from gray to GREEN (**Figure 3-28**).
3. Verify that the Flight Director is giving proper steering cues to intercept and track the course.

With GPS Steering (GPSS), a compatible GPS navigator (in this case, a Garmin 430W) drives the autopilot directly, telling it how to bank to stay centered on course. GPSS drives the autopilot far more accurately than the AP NAV mode, because the GPS always knows the ground track and how to adjust to maintain that track, implicitly accounting for changing wind conditions. The GPS also includes turn anticipation, enabling it to roll out centered on the new course without overshooting. As we'll soon see when flying an instrument approach, GPSS with a WAAS GPS can even fly procedure turns and holding patterns hands-off.



Now that we're established at our final cruise altitude and in the en route phase of our flight, we'll switch to the ARC mode of the HSI, to maximize a forward view.

1. Press the 360 Hot Key, and observe the HSI changes to its ARC view, and the legend adjacent to the Hot Key changes to ARC in GREEN.
2. Adjust the map range to suit your preference.

### Select a Compass Mode

- Push the 360/ARC Hot Key (third Hot Key) to alternately select either the 360° (Figure 3-29) or the ARC (Figure 3-30) compass display.

We set cruise power and lean the mixture. As the airplane stabilizes in cruise, we check the Data Bar to monitor performance. True Airspeed (TAS) is close to book performance for this altitude and power setting. OAT is close to ISA. Winds aloft are close to forecast, about 30° off the nose at 15 knots, so we'll expect to lose some ground speed due to a stronger headwind component when we turn northwest toward Reno.

Check TAS, GS, and winds and temperature aloft on the Data Bar (Figure 3-31).

Continuing en route, we monitor progress along our flight plan on the extended forward view of ARC mode, watching as GPSS keeps us exactly centered on course through numerous turns on the airways.

## 3.2.4. Arrival and Approach to Landing

As we near Reno, we prepare for our arrival. Within range, we pick up the ATIS and learn that the ILS16R approach is in use. Our route along V105 brings us in to Mustang VOR (FMG), which has a published transition to TAKLE, an Initial Approach Fix (IAF) for this procedure. Because we'd like some practice with our new PFD, we'll ask to fly the full procedure with pilot nav.



### NOTE

Each HSI view (360 and ARC) retains its own Range and Map Feature Level settings when switching between the two view modes.



Figure 3-29  
360° Compass Mode



Figure 3-30  
ARC CDI Compass Mode



Figure 3-31 Data Bar



Figure 3-32  
MIN Hot Key (shown disabled)



Figure 3-33  
MIN Display Selected for Editing

We load the KRNO ILS16R approach into the GPS, selecting TAKLE as our IAF. The ILS frequency (110.9) is placed in the standby window of the 430W. Briefing the approach, we note our Decision Altitude (DA) is 5,515 feet. We set our approach MINIMUMS on the EFD1000 to 5,520 feet (MIN are set in increments of 10 feet, so we round up). And we set our Selected Airspeed for the approach at 105 KIAS.

1. Press the MIN Hot Key (**Figure 3-32**). The MIN display appears on the lower right-hand corner of the ADI in magenta (**Figure 3-33**), ready for setting, and the MIN legend adjacent to the Hot Key changes from gray to magenta.
2. Turn the Right Knob to set 5,520 on the MIN display.
3. Press the Left knob twice to select IAS for editing.
4. Turn the Left knob to set 105 knots as our target airspeed.

We're all set up for the approach. Nearing Mustang (FMG), Oakland Center hands us off to Reno Approach, and we request own nav for the ILS16R. Approach gives us the new altimeter setting of 30.08, clears us down to 9,000 feet, and after FMG direct TAKLE. We initiate the descent, set 30.08 in the standby altimeter, and set the EFD1000:

1. Press the Right knob twice to select ALT for editing.
2. Turn the Right knob left to set 9,000 as our Selected Altitude.
3. Press the Right knob once more to select BARO for editing
4. Turn the Right knob left to set 30.08 as our baro setting.

Fifteen seconds before reaching 9,000 feet, the Altitude Alerter flag illuminates and the alert tone sounds. We begin our level-off, and re-engage ALT hold on the autopilot upon reaching 9,000 feet. We leave the autopilot in HDG mode, and continue with GPSS enabled on the EFD1000.

Crossing FMG, the GPS sequences to TAKLE, our Course Pointer swings automatically from 302° to 316°, and GPSS continues to steer us on course. We power back to slow down. Reno Approach calls, reports us six miles from TAKLE and clears us for the ILS16R approach, pilot nav.

We activate the approach on the GPS, and move the ILS frequency into the active window.

GPSS continues to steer the plane to the initial approach fix, TAKLE, and, crossing TAKLE, turns us outbound on a 344° course for the procedure turn (**Figure 3-34**). We see the procedure turn drawn on our base map ahead of us, and watch it turn magenta as GPSS turns and flies the procedure turn for us, with no further pilot action required.

As GPSS completes the procedure turn and rolls out centered on our final approach course of 164°, we change to APPR mode on the autopilot and begin a descent down to 8,500 feet.

1. Press the Right knob twice to select ALT for editing.
2. Turn the Right knob to set 8,500 as our Selected Altitude.
3. On reaching 8,500, re-engage ALT hold on the autopilot.

Along this intermediate segment of the approach, watch for the 430W to switch automatically from GPS to VLOC output on its CDI.

- Watch for the EFD1000 CDI Source Select field to change from GPS1 to VLOC1.

This automatic switch from GPS to VLOC should occur 2–10 NM outside the Final Approach Fix. If it has not occurred automatically by 2 NM outside the FAF, manually press the CDI button on the 430W to make the switch to the ILS frequency.

As navigation switches to the ILS, the LDI and VDI (**Figure 2-2, Refs. 34 and 35**) will appear on the Attitude Display.

1. The LDI Navigation Source Indication (**Figure 2-2, Ref. 29**) will show ILS if it is receiving a valid glide slope signal, or LOC if it is not receiving the glide slope (GS).
2. The CDI Source Information Block (**Figure 2-2, Ref. 63**) will also show ILS or LOC.



Figure 3-34  
ARC Mode Showing Procedure Turn, GPSS Enabled



Figure 3-35  
VDI Showing Glide Slope Full  
Deflection High (Hollow Indicator)



Figure 3-36  
MINIMUMS Alert

When the GS is full-scale deflection above us, the GS indicator on the VDI will show as a hollow diamond at the top of the scale (**Figure 3-35**). When the GS comes alive, the indicator will change to a solid green diamond and begin to move down the scale. Just before intercepting the GS, drop the gear, and check for three green lights. On GS intercept, verify that the autopilot switches to GS capture and begins to track down the glide slope.

Continue to monitor the approach, and verify that the autopilot is tracking both localizer and glide slope. The weather is well above minimums and we intend to land out of the approach, but will let the autopilot fly it down to minimums. On reaching our pre-set minimums (5,520 feet),

- The MINIMUMS alert displays below the Aircraft Reference Symbol on the ADI (**Figure 3-36**).
- The alert tone sounds three times.

We disconnect the autopilot and hand-fly the plane to landing, continuing to fly the Flight Director and track the glide slope down to a smooth landing.

### 3.3. Conclusion

The EFD1000 Pro PFD is a powerful addition to any cockpit, providing far more capability, information and automation than the mechanical instruments it typically replaces. While it is simple and intuitive enough to start using with only a short orientation, fully understanding and exploiting all of its features requires some study and experience.

**Chapter 4** covers all of the EFD1000 Pro PFD's features in detail. **Chapter 5** explains how to customize the PFD to suit your preferences. **Chapter 6** addresses Emergency and Abnormal procedures. Please read through all these chapters for a fuller understanding of how to use your EFD1000.

## Chapter 4

### Reference Guide

The EFD1000 PFD is a panel-mounted Electronic Flight Instrument System (EFIS) that presents the pilot with displays of attitude, altitude, indicated airspeed, heading, rate of turn, slip/skid, and navigation course deviation information. The system also displays supplemental flight data such as winds, TAS, OAT, etc., moving maps, pilot-selectable indices ("bugs"), and various annunciations to increase situational awareness and enhance flight safety. Moving map situational awareness information is displayed when the unit is connected to compatible GPS equipment.

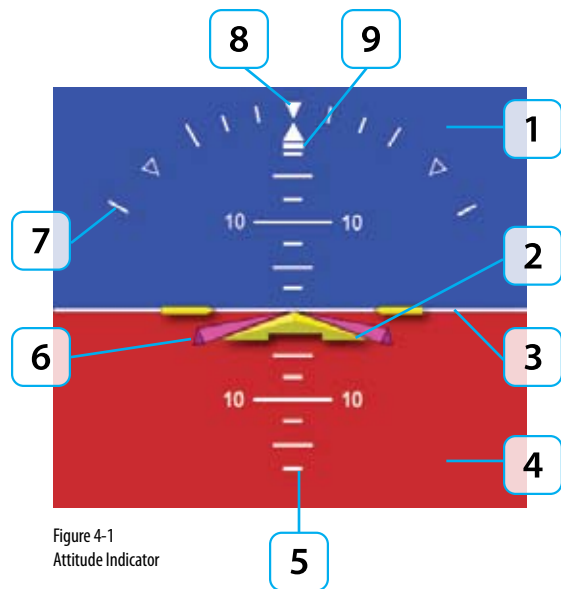
The EFD1000 PFD system components include the EFD1000 PFD display head, a Remote Sensor Module (RSM), a Configuration Module (CM), and the optional Analog Converter Unit (ACU). **Chapter 1, Welcome & Introduction**, provides a detailed discussion on the EFD1000 PFD system components.

When interfaced with a compatible autopilot, the EFD1000 PFD system provides heading and course datum information to the autopilot, which enables the autopilot to follow the Course and Heading values set by the pilot on the EFD1000 PFD, in much the same way as with a mechanical HSI. When interfaced with a compatible GPS, the EFD1000 PFD can provide GPS Steering (GPSS) to an autopilot.



#### NOTE

*The optional ACU enables the interface of the EFD1000 PFD system with legacy panel-mounted GPS navigators, VOR/Localizer radios, and autopilots.*



## 4.1. Attitude Display

### 4.1.1. Attitude Indicator

The Attitude Indicator consists of an aircraft reference symbol on a blue (sky) and brown (ground) background. The white horizon line separates the sky from the ground and extends to the edge of the display. The Roll Scale curves over the top of the Attitude Indicator while the Pitch Scale extends vertically in the middle. The slip/skid rectangle is directly underneath the roll pointer (**Figure 4-1**).

- |                                    |                              |
|------------------------------------|------------------------------|
| <b>1</b> Sky                       | <b>6</b> Flight Director     |
| <b>2</b> Aircraft Reference Symbol | <b>7</b> Roll Scale          |
| <b>3</b> Horizon Line              | <b>8</b> Roll Pointer        |
| <b>4</b> Ground                    | <b>9</b> Slip/Skid Indicator |
| <b>5</b> Pitch Scale               |                              |

The Attitude Indicator cannot be disabled by the pilot. The Aircraft Reference Symbol is fixed relative to the Attitude Indicator and overlays all other Attitude Indicator symbols. A pitch offset adjustment ( $\pm 10^\circ$ ) is provided to installers to compensate for variations in installations and slight panel tilts.

#### 4.1.1.1. Roll Scale

The Roll Scale is displayed at the top of the Attitude Indicator and is comprised of a moving scale set against a fixed, white, triangle roll pointer. Tick marks are displayed at 0°, 10°, 20°, 30°, 45° and 60° of roll. The 45° marks are triangles.

#### 4.1.1.2. Slip/Skid Indicator

The Slip/Skid Indicator is the small white rectangle under the roll pointer. The Slip/Skid Indicator moves left and right relative to the roll pointer in proportion to lateral acceleration. The width of the rectangle is equivalent to the width of the ball in a mechanical inclinometer.

#### 4.1.1.3. Pitch Scale

The pitch scale consists of minor pitch marks in 2.5° increments up to  $\pm 20^\circ$  and major pitch marks in 10° increments up to  $\pm 90^\circ$ . Red chevrons appear for nose-up pitch angles of 30° or more (**Figure 4-2**), and nose-down pitch angles of -25° or less (**Figure 4-3**). The pitch chevrons aid the pilot in unusual attitude recovery.

The range of movement of the background sky and ground boundaries are limited such that some sky or ground is always visible.

#### 4.1.1.4. Flight Director

When connected to a compatible autopilot and configured through an ACU during installation, the EFD1000 PFD displays a single-cue (two-axis) flight director on the Attitude Indicator (**Figure 4-4**). The pilot may follow the flight director's pitch and roll cues, even when the autopilot is not engaged, to remain on heading or altitude, climb or descend, turn, or navigate along a programmed flight path.



Figure 4-2  
Pitch Markings - Large Pitch Down



Figure 4-3  
Pitch Markings - Large Pitch Up



#### NOTE

Refer to the autopilot's AFMS for information on the operation of the flight director. The Flight Director is a visual representation of the pitch and roll commands from the autopilot. The Flight Director's pitch and bank limits are based on the emulation mode set at installation, and is limited to  $\pm 45^\circ$  roll and  $\pm 25^\circ$  pitch.



Figure 4-4  
Flight Director

#### 4.1.1.5. Air Data and Attitude/Heading Reference System (ADAHRS)

The Aspen ADAHRS uses Microelectromechanical systems (MEMS) technology to provide attitude reference. The technology is different from legacy gyro systems and an understanding of the capability and limitations can be helpful to the operator.

Generally, MEMS attitude solutions use multiple inputs to derive and validate the attitude solution. The Aspen System uses more than a dozen inputs to determine and monitor the aircraft attitude. In this way the system can validate the derived attitude indication by cross-checking the various inputs to the solution for consistency with one another.

The Aspen ADAHRS solution uses inputs from its internal three-axis accelerometers, rate gyros and magnetometers, supplemented by pitot and static pressure inputs from the aircraft pitot-static system. Failures or incorrect input from any one of these sensors, such as might occur if the pitot tube or static system became blocked, will affect the attitude solution. These conditions are sensed by the system and a “Cross Check Attitude” annunciation is presented (**Figure 4-5**). It is possible for the attitude performance to be affected before the “Cross Check Attitude” annunciation, especially when there are accelerations imposed, such as during steep turns or abrupt pitch changes. An ADAHRS attitude discrepancy is generally obvious to the pilot, either by an anomalous behavior cross-checked against the stand by attitude, or by annunciation.

Operationally, it is important to preflight the aircraft to assure proper performance of the pitot and static systems, especially when anticipating low IMC. If there are issues

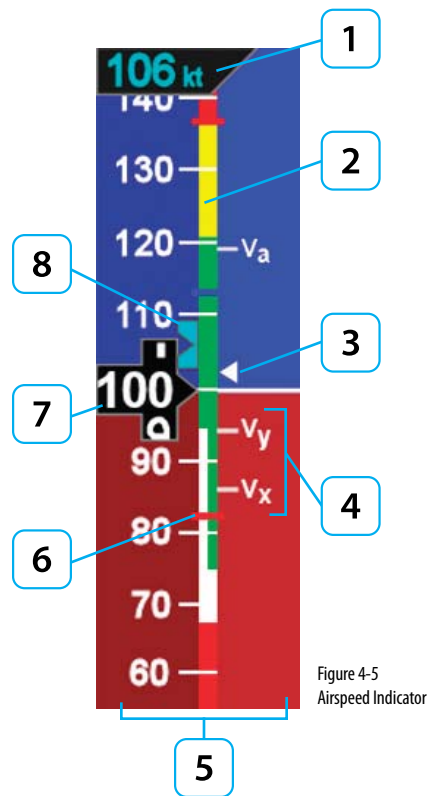


with airspeed or altitude that are consistent with an obstructed pitot or static line, the pilot should recognize that the attitude indication will soon be compromised. If in IMC, immediately use the backup indicator to fly the airplane. If at any time there is even a momentary "Cross Check Attitude" warning, use the backup attitude indicator until the cause of the warning is corrected.

In summary, loss or degradation of the attitude solution is unlikely. If the pitot or static system becomes blocked, an ADAHRS internal sensor fails, or the "Cross Check Attitude" indication is presented for even a moment, the attitude indication on the PFD should be considered to be compromised. In this circumstance the pilot must use the backup attitude indicator for attitude reference until the cause of the problem is resolved.

#### **4.1.1.6. Degraded ADAHRS Performance**

See sections **6.1. In Flight ADAHRS Reset**, **6.2. Pitot/Static System Blockage**, and **7.1.3. Geographic Limitations**.



#### 4.1.2. Airspeed Indicator

The airspeed indicator is comprised of a moving tape, airspeed bug, and numerical airspeed value (drum). Textual V-speeds, color Speed Bands, and Speed Markers are also rendered on the moving tape (**Figure 4-5**).

- 1 Selected Airspeed
- 2 Color Speed Bands
- 3 Initial Flap Extension Speed Marker
- 4 Textual V-speeds
- 5 Airspeed Tape
- 6 Speed Markers
- 7 Numerical Airspeed Value (drum)
- 8 Selected Airspeed Bug

Indicated airspeed is displayed in knots or miles per hour, set at installation, with tick marks rendered on the Airspeed tape every ten (10) units. Speed Bands and Speed Markers are configured during installation and cannot be changed or removed by the pilot. The textual V-speeds are pilot-configurable, and are discussed in **Chapter 5, Customizing the PFD**. Although the pilot can set the selected airspeed (bug), there is no visual or aural annunciation provided when the actual airspeed deviates from the selected airspeed value.

The numerical airspeed value is displayed in a rolling drum format in the center of the airspeed tape with numbers moving downward as speed increases, and upward as speed decreases. The display range of the indicated airspeed is 20 - 450 (knots or miles per hour). The numerical airspeed value is displayed in red when Vne is exceeded or when the airspeed drops below  $V_{s0}$  during stalls or landing roll-outs (**Figure 4-6**).

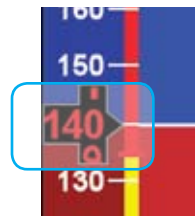


Figure 4-6  
Actual Airspeed Greater  
Than the Vne



Figure 4-7  
Airspeed Bug Selected to Edit



Figure 4-8  
New Airspeed Selected



## NOTE

A typical installation sets the tapes display to UNLOCKED, allowing the pilot to display or hide the Airspeed and Altitude tapes as desired. If the Airspeed and Altitude Tapes were LOCKED ON during installation, the tapes will remain on. If the Airspeed and Altitude Tapes were LOCKED OFF during installation, the tapes will not display.

### 4.1.2.1. Selected Airspeed

The Selected Airspeed value (bug) is rendered on the Airspeed Tape numerically and graphically. The numerical value is shown at the top of the Airspeed Tape. The bug is displayed adjacent to the Airspeed Tape when the Selected Airspeed value is within the visible range of the tape. The default value of the Selected Airspeed is 20 units, or the value previously set. Synchronizing the IAS field sets the Selected Airspeed value to the current indicated airspeed (**Section 2.2.1.3**). Setting the Selected Airspeed to a value less than 20 disables the bug and dashes the Selected Airspeed display.

#### Set Selected Airspeed (Bug)

1. Press the Left Knob until IAS displays above the Left Knob and the Selected Airspeed field and bug are enabled for editing, all rendered in magenta (**Figure 4-7**).
2. Rotate the Left Knob to change the value of the Selected Airspeed field. Rotate clockwise to increase, or counterclockwise to decrease, the value. Once the correct value is selected, and after 10 seconds of inaction, the field is disabled and the label, field, and bug are rendered in cyan (**Figure 4-8**).

### 4.1.2.2. Airspeed Display

The airspeed tape can be turned off, at the pilot's discretion, to facilitate screen declutter. This setting will be retained when the EFD1000 PFD system is turned off and then powered-on again.

### Hide/Display Airspeed Tape

- Press the TPS Hot Key to alternately hide or display the Airspeed and Altitude Tape (Figures 4-9 and 4-10).



Figure 4-9  
TPS Hot Key



Figure 4-10  
Airspeed Tape Disabled

**NOTE** Both the Airspeed and Altitude tape are affected by this action.

**NOTE** When the Airspeed tape is disabled, the numerical display of the selected airspeed remains on.

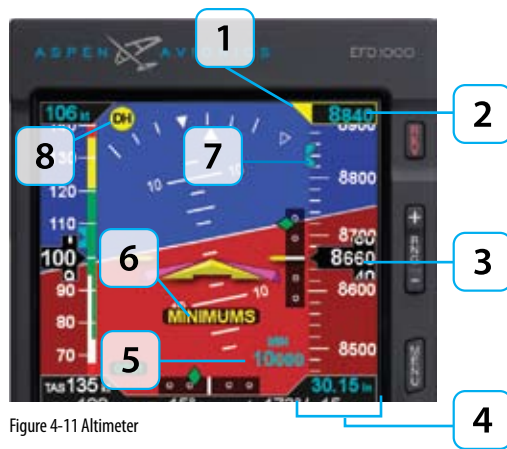


Figure 4-11 Altimeter



Figure 4-12 Altitude Failure

### 4.1.3. Altimeter

The altimeter is comprised of an altitude bug, a numerical altitude value (drum), a moving tape, a MINIMUMS annunciation and adjustable value, a Decision Height (DH) alert, and a visual/aural altitude alerter (**Figure 4-11**).

- |                                   |                                |
|-----------------------------------|--------------------------------|
| <b>1</b> Altitude Alerter         | <b>5</b> MINIMUMS Adjustment   |
| <b>2</b> Selected Altitude        | <b>6</b> MINIMUMS Alert        |
| <b>3</b> Numerical Altitude Value | <b>7</b> Altitude Bug          |
| <b>4</b> Altitude Tape            | <b>8</b> Decision Height Alert |

The Altitude Tape range is from -1,600 to 51,000 feet. Major tick marks are provided every 100 feet and minor tick marks every 20 feet. A barometric pressure adjustment is provided to the pilot for display of altitude above mean sea level.

The numerical altitude value is displayed in a rolling drum format in the center of the airspeed tape, with numbers moving downward as the altitude increases and upward as altitude decreases. The numerical altitude value shows the altitude to the nearest 20 feet.

If the altitude exceeds 51,000 feet, the numerical altitude value is dashed and the tape is frozen at this limit. All altitude information is removed and replaced with a red "X" with the textual annunciation of "ALT FAIL," when altitude data is invalid (**Figure 4-12**).

#### 4.1.3.1. Barometric Pressure Adjustment (BARO)

Barometric pressure adjustment may be made in either inches of mercury (in) (**Figure 4-13**) or millibars (mB) (**Figure 4-14**), as configured by the pilot. The adjustment range is 28.10 – 30.99 inches Hg or 946 – 1049 mB. The Barometric pressure default value and units of measure is 29.92 and inches Hg, or as previously set.

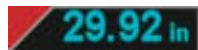


Figure 4-13  
Baro Shown in Inches of Mercury

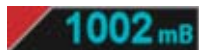


Figure 4-14  
Baro Shown in Millibars

#### Set Barometric Units of Measure

1. Push the MENU key. The Menu displays on the Navigation Display.
2. Rotate the Right Knob counterclockwise until Page 1 of the Menu displays (**Figure 4-15**).
3. Push the BARO Menu Key (Key 1). The menu label turns magenta and the EDIT VALUE label displays above the Right Knob (**Figure 4-16**).
4. Rotate the Right Knob to select either IN or mB (**Figure 4-17**).
5. Push the MENU key to exit the Menu.



Figure 4-15  
Menu, GENERAL  
SETTINGS, Page 1 of 7



Figure 4-16  
Editing BARO



Figure 4-17  
BARO Set to mB (millibars)

**NOTE**

Adjust the EFD1000's barometric pressure whenever the mechanical altimeter's barometric pressure is adjusted.



Figure 4-18 BARO Field Enabled

**NOTE**

Since the altitude tape display is limited to approximately 400 feet, the altitude bug symbol only displays on the altitude tape when the selected altitude is within the visible range of the current altitude.

### Set The Barometric Pressure

1. Press the Right Knob until BARO displays above the Right Knob and the barometric pressure field is enabled for editing, both rendered in magenta (**Figure 4-18**).
2. Rotate the Right Knob to change the value of the barometric pressure field. Rotate clockwise to increase, or counterclockwise to decrease, the value. Once the correct value is selected, and after 10 seconds of inaction, the field is disabled and the label and field are rendered in cyan.



#### 4.1.3.2. Selected Altitude

The Selected Altitude value is displayed at the top of the Altitude Tape. The Selected Altitude range is 100 to 51,000 feet, in 20 foot increments. The default value for the Selected Altitude value is 100 feet, or the previously set value. Additionally, an altitude bug is displayed adjacent to the Altitude Tape and at the selected altitude, when within the visible range of the current altitude.

##### Set Selected Altitude (Bug)

1. Press the Right Knob until ALT displays above the Right Knob and the Selected Altitude numerical field and bug are enabled for editing, all rendered in magenta (**Figure 4-19**).
2. Rotate the Right Knob to change the value of the numerical Altitude field. Rotate clockwise to increase, or counterclockwise to decrease, the value. Once the correct value is selected, and after 10 seconds of inaction, the field is disabled and the label, field, and bug are rendered in cyan.

#### 4.1.3.3. Altitude Level-Off and Deviation Alert

The altitude level-off alert is ARMED and rendered on-screen as a yellow alert flag next to the Selected Altitude value when the aircraft is within 15 seconds or 200 feet (whichever is greater) of the selected altitude (**Figure 4-20**). If an optional Sonalert tone generator device is installed, a one-second tone also sounds. Once the current altitude is within  $\pm 25$  feet of the selected altitude, the alert flag extinguishes and the selected altitude is CAPTURED (**Figure 4-21**).

After reaching the selected altitude, if the aircraft's current altitude differs from the selected altitude by more than 200 feet, the yellow alert flag flashes. If an optional Sonalert tone generator device is installed, a one-second tone also sounds.

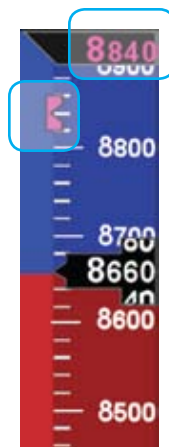


Figure 4-19  
Altitude Bug/Alerter Field Enabled



Figure 4-20  
Altitude Alert

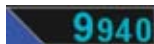


Figure 4-21  
Selected Altitude Capture and  
Aircraft Level-off



#### NOTE

*Rotating the knob quickly will change the altitude value in larger increments.*

**NOTE**

Pressing the MIN Hot Key turns on the MINIMUMS display and enables the MIN data field for editing. The MIN label displays above the Right Knob in Magenta and the MIN data field's numerical value is also rendered in Magenta. See **Step 2 of Set Altitude Minimum**.



Figure 4-22  
MIN Hot Key – Selected  
Minimums Disabled

**4.1.3.4. MINIMUMS Alert**

The EFD1000 PFD provides an adjustable MINIMUMS field to enhance situational awareness during instrument approaches. Once the MIN data field value is set to a Decision Height or Minimum Descent Altitude, the EFD1000 PFD provides an alert when the aircraft descends below this altitude. To activate this feature, the pilot must enable the MINIMUMS display and set the desired altitude via MIN data field value adjustment.

**Display/Hide Minimums**

- Press the MIN Hot Key to alternately hide or display the MINIMUMS display (Figures 4-22 and 4-23).



Figure 4-23  
Selected Minimums Enabled

The range for the MIN data field is 0 – 15,000 feet, in increments of 10 feet. Synchronizing sets the MIN data field value to the current altitude (**Section 2.2.1.3**). The default value is 100 feet or the previously set value.

### Set Altitude Minimum

1. Press the Right Knob until MIN displays above the Right Knob and the MINIMUMS field is enabled for editing, both rendered in magenta (**Figure 4-24**).
2. Rotate the Right Knob to change the value of the MINIMUMS field. Rotate clockwise to increase, or counterclockwise to decrease, the value. Once the correct value is selected, and after 10 seconds of inaction, the field is disabled (**Figure 4-25**).

If the aircraft's altitude becomes lower than the MINIMUMS field's setting, the MINIMUMS annunciation displays below the Aircraft Reference Symbol and, if configured, the Sonalert tone sounds three times (**Figure 4-26**). If the aircraft reaches an altitude 100 feet greater than the MINIMUMS field setting, the MINIMUMS alert is removed.

#### 4.1.3.5. Decision Height Annunciation

If a radar altimeter is installed and connected to the EFD1000 PFD, a Decision Height annunciation displays whenever the external input commands the DH annunciator ON. The Decision Height alert is a fixed-position, yellow "DH," displayed near the upper right corner of the Attitude Indicator (**Figure 4-27**).



Figure 4-27  
DH Alert Active



Figure 4-24 MIN Field Enabled



Figure 4-25 New MIN Setting



Figure 4-26 Minimums Alert Active

**NOTE**

A typical installation sets the tapes display to UNLOCKED, allowing the pilot to display or hide the Airspeed and Altitude tapes as desired. If the Airspeed and Altitude Tapes were LOCKED ON during installation, the tapes will remain on. If the Airspeed and Altitude Tapes were LOCKED OFF during installation, the tapes will not display.

**NOTE**

Both the Airspeed and Altitude tape are affected by this action.

**NOTE**

When the Altitude tape is disabled, the numerical display of the selected altitude and altitude minimums remain on. The decision height and minimums annunciations operate as configured.

#### 4.1.3.6. Altitude Display

The altitude tape can be turned off, at the pilot's discretion, to facilitate screen declutter.

##### Hide/Display Altitude Tape

- Press the TPS Hot Key to alternately hide or display the Altitude and Airspeed Tapes (**Figures 4-28 and 4-29**).



Figure 4-28 TPS Hot Key



Figure 4-29 Altitude Tape Disabled

## 4.2. Data Bar

The Data Bar presents True Airspeed (TAS), GPS Ground Speed (GS), Outside Air Temperature (OAT), Wind Direction, Wind Speed, and Barometric Pressure Setting as shown in **Figure 4-30**. The data bar is always present on the display. Invalid or out-of-range Data Bar values are dashed.

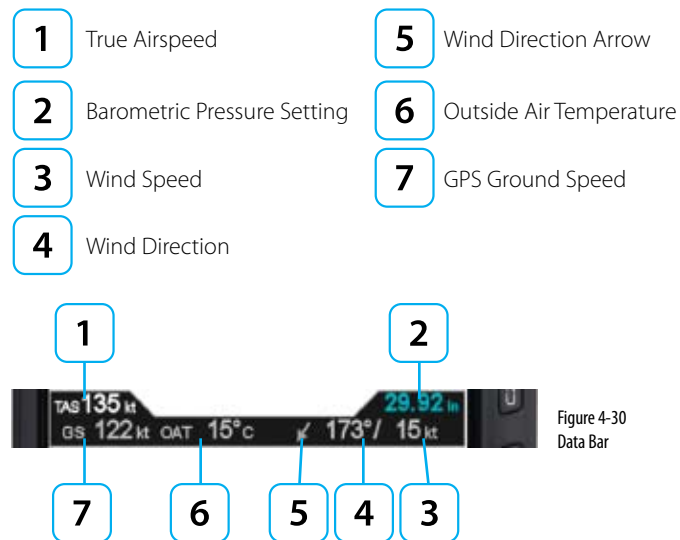


Figure 4-30  
Data Bar

### 4.2.1. True Airspeed

The True Airspeed (TAS) is displayed on the upper left of the Data Bar with a value range of 20 – 999 knots or mph, using the same unit of measurement as the Airspeed Indicator. The TAS is a correction of the IAS for nonstandard pressure and temperature.

### 4.2.2. Ground Speed

The Ground Speed (GS) is digitally displayed on the lower left corner of the Data Bar with a value range of 5 – 999 knots or mph, using the same unit of measurement as the Airspeed Indicator.

### 4.2.3. Outside Air Temperature

The Outside Air Temperature (OAT) is digitally displayed on the center of the Data Bar. The temperature is obtained from the temperature sensor located in the RSM and rendered in degrees Celsius (C) ranging from -99 – 999 degrees.

#### 4.2.4. Wind Speed, Direction, and Arrow

The Wind Speed, Direction, and Direction Arrow are displayed in the lower right portion of the Data Bar. If the data are out of range or invalid, the values are dashed and the wind arrow is removed.

The Wind Speed has a range of 10 – 999 knots or mph, using the same unit of measurement as the Airspeed Indicator.

The Wind Direction and Arrow (**Figure 4-31**) have a range of 001° – 360°, magnetic. The arrow is displayed relative to the current direction of flight. For example, if the current direction of flight is 090 and the wind is from 090, the arrow points straight down on the display.

#### 4.2.5. Barometric Pressure Setting Display

The Barometric Pressure field is digitally displayed on the upper right corner of the Data Bar and is pilot-adjustable as discussed in **Section 4.1.3.1**. When the Altitude Tape is disabled, the barometric pressure setting field remains visible. **Section 4.1.3.1** provides complete information and step-by-step instructions for setting the barometric pressure.



#### NOTE

*The wind computations require a GPS-supplied ground track and ground speed to compute the wind direction and speed. If a GPS is not connected to the EFD1000 PFD or the data are invalid, the wind direction and speed are dashed and the wind direction arrow is removed..*



Figure 4-31  
Wind Direction Arrow

**NOTE**

The shape, location, and size of the course pointer and deviation scale and indicator depend on the compass mode selected.

## 4.3. Navigation Display

The Horizontal Situation Indicator (HSI), on the Navigation Display of the EFD1000 PFD, combines a Direction Indicator with a Course Deviation Indicator (CDI) (**Figure 4-32**).

The Direction Indicator consists of a compass, numerical direction indication, heading bug, aircraft track marker (when GPS ground track information is available), rate of turn indicator, and an aircraft ownship symbol.

The CDI is comprised of a selected course pointer, deviation scale and indicator, TO/FROM indicators, and selected navigation source label and information block.



Figure 4-32  
Horizontal Situation Indicator

- |          |                              |           |                            |
|----------|------------------------------|-----------|----------------------------|
| <b>1</b> | Navigation Source Info Block | <b>8</b>  | Deviation Scale            |
| <b>2</b> | Heading Bug                  | <b>9</b>  | Aircraft Ownship Symbol    |
| <b>3</b> | Direction Indicator          | <b>10</b> | Selected Navigation Source |
| <b>4</b> | Rate of Turn Indicator       | <b>11</b> | Compass Scale              |
| <b>5</b> | Selected Heading             | <b>12</b> | Deviation Indicator        |
| <b>6</b> | Selected Course Pointer      | <b>13</b> | Track Marker               |
| <b>7</b> | TO/FROM Indicators           |           |                            |



All instrument values on the HSI are displayed in degrees. The value range is from 001° - 360°, always displayed in three digits, and utilizing leading zeros when applicable. Magnetic North is numerically represented as 360°.

### 4.3.1. Compass

The EFD1000 PFD offers three compass modes: 360°, ARC HSI, and ARC CDI. The default compass mode is 360°. The aircraft's heading is always expressed as magnetic heading. The magnetic headings inside of the compass scale drop the last zero for brevity (i.e., 30°, 60°, 120°, 150°, 210°, 240°, 300°, and 330° are labeled 3, 6, 12, 15, 21, 24, 30, and 33, respectively). The four cardinal compass headings are shown as letters (i.e., "N" for 360°, "E" for 090°, "S" for 180°, and "W" for 270°).

#### 4.3.1.1. 360° Compass Mode

The 360° Compass mode displays a full 360° compass rose with all other components of the Direction Indicator. The 360° compass rose rotation centers on the aircraft ownship symbol, so that the numerical direction indication corresponds to the current aircraft heading (**Figure 4-33**).



Figure 4-33  
360° Compass Mode



Figure 4-34  
ARC HSI Compass Mode

#### 4.3.1.2. ARC Compass Mode

The two ARC Compass modes show an abbreviated, 100° arc compass scale. All other elements of the Direction Indicator are presented. The ARC compass scale's rotation centers on the aircraft ownship symbol, so that the numerical direction indication corresponds to the current aircraft heading. The default ARC Compass mode is ARC HSI.

The ARC HSI Compass mode presents a rotating CDI, similar to that used in the 360° Compass mode (**Figure 4-34**).



Figure 4-35  
ARC CDI Compass Mode

Figure 10 shows the engine speed (RPM) gauge and the engine speed (RPM) menu. The gauge displays a needle pointing to 1000 RPM. The menu shows 'RPM' and 'EDIT VALUE'.

The ARC CDI mode uses a fixed, non-rotating CDI indicator, resembling a contemporary GPS navigation deviation display. The ARC CDI Compass mode is intended to maximize the lower display area for map and flight plan data (**Figure 4-35**).

1. Push the MENU key. The Menu displays on the Navigation Display.
2. Rotate the Right Knob counterclockwise until Page 1 of the Menu displays (**Figure 4-36**).
3. Push the ARC MODE Menu Key (Key 4). The menu label turns magenta and the EDIT VALUE label displays above the Right Knob (**Figure 4-37**).
4. Rotate the Right Knob to select either HSI or CDI (**Figure 4-38**).
5. Push the MENU key to exit the Menu.

## Select Compass Type

- Push the 360/ARC Hot Key (**Figure 4-39**) to alternately select either the 360° or ARC Compass. The Navigation Display changes and the Hot Key label reflects the currently selected compass type (**Figures 4-40 and 4-41**).



Figure 4-39  
360/ARC Hot Key



Figure 4-40  
ARC Compass Mode



Figure 4-41  
360° Compass Mode



Figure 4-42  
Reduced Length Course Pointer



Figure 4-43  
Stub Course Arrowhead



Figure 4-44  
Stub Course Tail

## 4.3.2. Course Pointer

For all compass modes, the arrowhead of the course pointer aligns with the corresponding value on the compass scale regardless of the aircraft heading. The ARC Compass HSI and CDI course pointers are different and described in **Table 4-1**.

COMPASS	DESCRIPTION
ARC HSI	The course pointer length shortens as necessary when rotated to remain within the display area ( <b>Figure 4-42</b> ).
ARC CDI	The course pointer is shown as a stub arrow or tail whenever the CRS value or its reciprocal falls within the displayable range of the compass scale arc ( <b>Figure 4-43 and 4-44</b> ).

Table 4-1 ARC Compass Pointer Display

### 4.3.3. TO/FROM Indicator

Each of the compass modes has a TO/FROM indicator. The TO/FROM indicator shows whether the aircraft is heading toward a waypoint or radio navaid, or from a waypoint or radio navaid. For each compass mode, the TO/FROM indication is slightly different, as described in **Table 4-2**.

COMPASS	DESCRIPTION
360°	The TO indicator is an arrowhead on the top half of the Selected Course Pointer, oriented in the same direction as the course arrowhead ( <b>Figure 4-45</b> ). The FROM indicator is an arrowhead on the bottom half of the Selected Course Pointer, oriented in the direction opposite to the course arrowhead ( <b>Figure 4-46</b> ).
ARC HSI	The TO indicator is shown as two arrowheads, one on each half of the Selected Course Pointer, oriented in the same direction as the course arrowhead ( <b>Figure 4-47</b> ). The FROM indicator is shown as two arrowheads, one on each half of the Selected Course Pointer, oriented opposite to the direction of the course arrowhead ( <b>Figure 4-48</b> ).
ARC CDI	The TO indication is shown as "TO" on the left side of the deviation scale ( <b>Figure 4-49</b> ). The FROM indication is shown as "FROM" on the right side of the deviation scale ( <b>Figure 4-50</b> ).

Table 4-2 TO/FROM Indicator Description

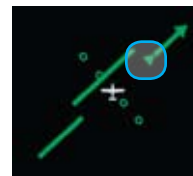


Figure 4-45  
360° TO Indication



Figure 4-46  
360° FROM Indication



Figure 4-47  
HSI TO Indication



Figure 4-48  
HSI FROM Indication



Figure 4-49 CDI TO Indication

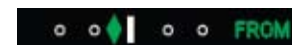


Figure 4-50 CDI FROM Indication

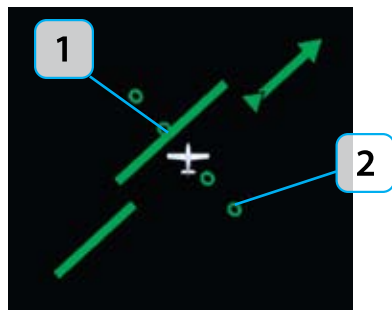


Figure 4-51  
Deviation Indicator, 360° and ARC HSI



Figure 4-54  
Exceeded Deviation, 360° and ARC HSI

#### 4.3.4. Course Deviation Indicator and Scale

Selected course deviation is depicted by a Course Deviation Indicator and Scale. Deviation is indicated by positioning the Course Deviation Indicator on the Scale corresponding to the lateral deviation value.

The 360° and ARC HSI compass modes display the CDI as a green line centered on the display and parallel with the course indicator. The scale is a set of four hollow, green dots that are perpendicular to the CDI (**Figure 4-51**).

1 Course Deviation Indicator

2 Course Deviation Scale

The ARC CDI Compass mode's CDI and Scale are located at the bottom of the lower display. The indicator is a green diamond and the scale is a set of four hollow, white dots with a white index mark at the center (**Figure 4-52**). When in the ARC CDI Compass mode, on a Localizer Back Course approach, a "BC" label is presented to the left of the scale and the indicator corrects for reverse sensing (**Figure 4-53**).

When the lateral deviation exceeds the maximum displayable range of 2.5 dots, the deviation bar or diamond, as applicable, becomes hollow and darker (**Figure 4-54 and 4-55**).



Figure 4-55  
Exceeded Deviation, ARC CDI



Figure 4-52  
Course Deviation Indicator, ARC CDI



Figure 4-53  
Course Deviation Indicator, ARC CDI with Back Course

### 4.3.5. CDI Navigation Source

When the EFD1000 PFD powers up, the default CDI Navigation Source is the last selected or the first configured navigation source, if no previous selection was made. The pilot can select from any of the installed navigation sources, using the bottom center button. The EFD1000 PFD supports navigation information display from VHF Omni-directional Radio Range (VOR) nav aids, Localizers (LOC), Glide Slope receivers (GS), and Global Positioning Systems (GPS). There can be up to four dedicated, two integrated, or a combination of one integrated and two dedicated navigation systems installed (**Table 4-3**).

INSTALLED NAVIGATION SOURCES		CDI LABEL	POSSIBLE CONFIGURATION			
Dedicated	NAV VHF Radio System	VLOC1	x		x	
Dedicated	NAV VHF Radio System	VLOC2	x			x
Dedicated	Global Positioning System	GPS1	x		x	
Dedicated	Global Positioning System	GPS2	x			x
Integrated System 1	GPS/VHF NAV Radio System GPS selected or	GPS1 or	x	x	x	
	GPS/VHF NAV Radio System VHF NAV selected	VLOC1				
Integrated System 2	GPS/VHF NAV Radio System GPS selected or	GPS2 or	x	x		
	GPS/VHF NAV Radio System VHF NAV selected	VLOC2				

Table 4-3 Possible CDI Navigation Source Configuration

#### NOTE

For integrated systems, the CDI navigation source label indicates the current operating mode ("GPS" or "VLOC") of the GPS/VHF NAV system.

When an integrated system is selected, but not reporting its operating mode, the label VLOC# displays.

Refer to the GPS or VHF NAV AFMS for information on the operation of the connected navigation equipment.

#### NOTE

There are many radio configurations available. Your authorized Aspen Avionics Dealer can tell you the configuration used on your aircraft.



Figure 4-56  
Navigation Source Information Block



Figure 4-57  
CDI Navigation Source  
Information Block

### Select The CDI Navigation Source

- Press the CDI Navigation Source Select button until the desired navigation source is displayed above the button (e.g., GPS1, GPS2, VLOC1, VLOC2) (**Figure 4-56**).

- CDI Source Select Button
- CDI Source Label
- CDI Source Information Block

Whenever the CDI navigation source navigation data is valid, a navigation information block for the currently selected navigation source is shown in the upper left corner of the lower display as described in **Figure 4-57** and shown in **Table 4-4**.

- CDI Source

Radio Mode	Information Block Label	
GPS		GPS1 or GPS2
VHF	VOR	VOR1 or VOR2
	Localizer	LOC1 or LOC2
	Localizer Back	LOC1(BC) or LOC2
	ILS	ILS1 or ILS2

Table 4-4  
VHF NAV Radio Modes



- 2 Waypoint identifier or tuned frequency (when available)
- 3 Bearing (in degrees)/Distance (in Nautical Miles) to waypoint or navaid (when available)
- 4 Estimated Time En route (Hours:Minutes)

When both the navigation source identifier and the tuned frequency of the associated VHF NAV radio are available, only the source identifier information shall be displayed on the second line of the information block.

When available, the bearing and distance to station is displayed on the third line of the information block in the format ddd°/nnnn or ddd°/nn.n, where ddd is the bearing in degrees and nnnn or nn.n is the distance in nautical miles (e.g. 360°/1103 or 322°/3.2 shown in **Figure 4-58**). The distance to waypoint is displayed as follows:

- Distance to waypoint < 100 NM, display is in tenths of a mile, i.e. ##.#.
- Distance to waypoint is 100 - 9999 nm, display in whole miles, i.e. ####.
- Distance to waypoint is > 9999 NM, display is dashed, i.e. ----.

When available, the estimated time en route information shall be displayed on the fourth line of the information block in the format h:mm (where h is hours and mm is minutes).

When CDI navigation source data is invalid or not available from a configured navigation source, the HSI course deviation bar and the FROM/TO indication are removed from the display (**Figure 4-58**). Additionally, the selected CDI Navigation Source label is slashed with a red line (**Figure 4-59**).

When information for a configured and selected navigation source is not available or invalid, the source information block is blank (**Figure 4-60**).



Figure 4-59  
Invalid CDI Navigation  
Source Label



Figure 4-58 No Course Deviation Bar or FROM/TO Info



Figure 4-60 Blank Info Block Fields



Figure 4-61  
Menu, GENERAL  
SETTINGS, Page 1 of 7



Figure 4-62  
Editing AUTOCRS



Figure 4-63  
AUTOCRS Enabled

### 4.3.6. Auto Course

The pilot can either use the AUTOCRS or manually set a CRS value. By default, AUTOCRS is enabled. When the selected CDI navigation source is a connected GPS receiver, and AUTOCRS is enabled, CRS is not adjustable (current course value is automatically slewed and controlled by the desired track from the GPS). When AUTOCRS is enabled, the CDI navigation source is a GPS system, and that system is configured for automatic waypoint sequencing (i.e., not OBS, HOLD or SUSPEND modes) then Auto Course Select is active.

#### Enable AUTOCRS

1. Push the MENU Key. The Menu displays on the Navigation Display.
2. Rotate the Right Knob counterclockwise until Page 1 of the Menu displays (Figure 4-61).
3. Push the AUTOCRS Menu Key (Key 3). The menu label turns magenta and the EDIT VALUE label displays above the Right Knob (Figure 4-62).
4. Rotate the Right Knob to select ENABLE (Figure 4-63).
5. Push the MENU key to exit the Menu.

When AUTOCRS is enabled, the CRS value is set to the desired track output from the CDI Navigation Source. The CRS value is shown in the upper left of the lower display area in green under the CRS label. Additionally, an inverted green A is shown beside the CRS label in the upper left of the lower display area and in the legend above the left knob. This indicates that the course is being automatically adjusted (Figure 4-64).

## Disable AUTO CRS

1. Push the MENU Key. The Menu displays on the Navigation Display.
2. Rotate the Right Knob counterclockwise until Page 1 of the Menu displays (**Figure 4-65**).
3. Push the AUTO CRS Menu Key (Key 3). The menu label turns magenta and the EDIT VALUE label displays above the Right Knob (**Figure 4-66**).
4. Rotate the Right Knob to select DISABLE (**Figure 4-67**).
5. Push the MENU key to exit the Menu.

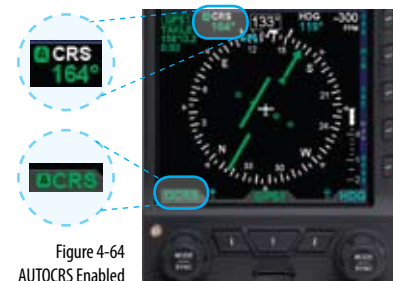


Figure 4-64  
AUTO CRS Enabled



Figure 4-65  
Menu, GENERAL SETTINGS, Page 1 of 7



Figure 4-66  
Editing AUTO CRS



Figure 4-67  
AUTO CRS Disabled



Figure 4-68  
CRS Field Enabled for Editing

### 4.3.7. CDI Selected Course

When the CDI source changes from a GPS source with AUTOCRS to another CDI source, the CRS value reverts to the last set value. When the CDI source is set to a VHF receiver operating in the VOR or Localizer modes, editing the CRS value adjusts the current selected CRS value. When the CDI source is set to a GPS receiver, and AUTOCRS is disabled, the CRS value may be adjusted.

#### Select CDI Course

1. Press the Left Knob until CRS displays above the Left Knob and the Course field is enabled for editing, both rendered in magenta (**Figure 4-68**).
2. Rotate the Left Knob to change the value of the Course field. Rotate clockwise to increase, or counterclockwise to decrease, the value. Once the CRS value is set, and after 10 seconds of inaction, the CRS field is disabled and both the label and field are rendered in cyan.

### 4.3.8. Bearing Pointer Source Selection

When the 360° Compass mode is selected, single- and double-line bearing pointers are available (**Figure 4-69**). The bearing pointers are independent of the CDI and provide supplemental navigation information by pointing to active GPS waypoints or nav aids. By default, the bearing pointers are off and not displayed.

<b>1</b>	Single-Line Bearing Pointer	
<b>2</b>	Single-Line Bearing Pointer Source Information	
	Top Line	Distance (NM) to active waypoint
	Bottom Line	Waypoint identifier, station identifier, or the tuned frequency of the associated VHF NAV radio (when available)
<b>3</b>	Single-Line Bearing Pointer Legend Name	
<b>4</b>	Double-Line Bearing Pointer	
<b>5</b>	Double-Line Bearing Pointer Source Name	
	Top Line	Distance (NM) to active waypoint
	Bottom Line	Waypoint identifier, station identifier, or the tuned frequency of the associated VHF NAV radio (when available)
<b>6</b>	Double-Line Bearing Pointer Legend Name	



Figure 4-69  
Bearing Pointer  
Description

#### NOTE

*Distance to waypoint < 100 NM, display is in tenths of a mile, i.e. ##.##.*

*Distance to waypoint is 100 - 9999 nm, display in whole miles, i.e. ####.*

*Distance to waypoint is > 9999 nm, display is dashed, i.e. ----.*

#### NOTE

*When both the station identifier and the tuned frequency of the associated VHF NAV radio are available, only the station identifier information shall be displayed on the second line of the information block.*

**NOTE**

*A VOR that is tuned to a localizer frequency shall be considered an invalid bearing pointer source since Localizer signals provide no bearing information.*



Figure 4-70  
NO bearing pointers or  
source information

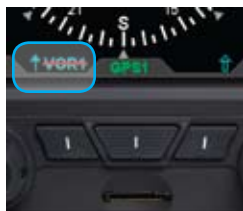


Figure 4-71  
Invalid Bearing Pointer  
Source Data Label



Figure 4-72  
Bearing Pointers OFF

The bearing pointers indicate only the bearing information provided by their selected navigation sources. They resemble and perform like traditional Radio Magnetic Indicator (RMI) needles. Each bearing pointer's head and tail is aligned with the corresponding bearing/radial value on the compass. The pilot can select a navigation source for each of the bearing pointers from the same VOR and GPS sources available to the CDI or simply turn the bearing pointer, source information, and source legend OFF.

Each bearing pointer is associated with a button, selected source name label, and information block. The button immediately to the left of the CDI source selection button is associated with and controls the Single-Line Bearing Pointer. Likewise, the button immediately to the right of the CDI source selection button is associated with and controls the Double-Line Bearing Pointer. The bearing pointers' source names and information blocks are shown directly above their respective buttons.

Unlike the CDI which can be adjusted by the pilot, no adjustments can be made to the bearing pointers. When a VOR is selected as a bearing pointer source, the arrow of the needle indicates the direction to the VOR navaid to which the receiver is tuned. The position of the bearing pointer tail, with respect to the compass, indicates the aircraft's current position on the VOR radial. When a GPS source is selected, the bearing pointer indicates the bearing to the active waypoint.

When the bearing pointer source data is not available or invalid, the bearing pointer and source information are removed (**Figure 4-70**) and the bearing pointer source legend is slashed with a red line (**Figure 4-71**).

When a bearing pointer is turned OFF, the legend shows the bearing pointer icon, but the selected source, the source information field, and the bearing pointer are removed (**Figure 4-72**).

### Select The Single-Line Bearing Pointer Source

- Press the Single-Line Bearing Pointer button (lower left button, **Figure 4-73**) until the desired navigation source displays above the Single-Line Bearing Pointer button.

### Select The Double-Line Bearing Pointer Source

- Press the Double-Line Bearing Pointer button (lower right button, **Figure 4-74**) until the desired navigation source displays above the Double-Line Bearing Pointer button.



Figure 4-73 173  
Single-Line Bearing Pointer and Button



Figure 4-74  
Double-Line Bearing Pointer and Button



Figure 4-75  
Selected Heading Bug  
and Numerical Display

### 4.3.9. Selected Heading and Heading Bug

The EFD1000 PFD offers a pilot-selectable heading bug. The heading bug symbol is positioned on the compass scale according to the heading bug value (HDG) selected by the pilot (**Figure 4-75**).

When the selected HDG value is outside the visible compass scale range, in ARC Compass mode, only a portion of the heading bug is shown at the edge of the compass arc, closest to the HDG value (**Figure 4-76**).



Figure 4-76  
Selected Heading Bug  
Outside of ARC Range



When selected for editing, the heading bug and the HDG value are shown in magenta. Additionally, a dashed magenta line extends from the ownship symbol to the heading bug, corresponding to the selected HDG value. When heading bug is SYNCed, the HDG value is set to the current heading.

### Heading Bug Set

1. Press the Right Knob until HDG displays above the Right Knob and the Heading field is enabled for editing, both rendered in magenta (**Figure 4-77**).
2. Rotate the Right Knob to change the value of the Heading field. Rotate clockwise to increase, or counterclockwise to decrease, the value. Once the HDG value is set, and after 10 seconds of inaction, the HDG field is disabled and both the label and field are displayed in cyan.

### 4.3.10. Aircraft Heading Display

The aircraft heading is displayed in degrees magnetic (**Figure 4-78**).

If the aircraft's heading is unavailable or invalid, all heading and navigation information, including the CDI and bearing pointers (if previously displayed), is removed and replaced with a single red "X" covering the entire lower display area, along with the annunciation, DIRECTION INDICATOR FAIL (**Figure 4-79**).



Figure 4-78  
Direction of Flight  
Numerical Display



Figure 4-77  
Heading Selected to Edit



Figure 4-79  
Direction Indicator Fail



Figure 4-80  
Rate of Turn Indicator (360° Compass Mode)



Figure 4-81  
Rate of Turn Indicator (ARC Compass Mode)

### NOTE

*All map and flight plan elements are received from the GPS and are only available from compatible GPSs (e.g., GNS 430, GNS 530).*

### NOTE

*A VORTAC is shown as a combined VOR and DME symbol. A TACAN is rendered as a DME symbol.*

## 4.3.11. Rate of Turn Indicator

The Rate of Turn Indicator consists of a curved white line originating from the corresponding side of the aircraft heading (i.e., a left turn indication starts on the left side of the index mark), and extends in the direction of the turn along the outer radius of the compass scale. The turn rate indication is provided for every compass mode, 360° (Figure 4-80) and ARC (Figure 4-81).

The Rate of Turn Indicator features tick marks for full and half-standard rates of turn (a standard rate of turn = 3° per second) in both directions.

The Rate of Turn Indicator has a range of 0° – 6° per second. When the turn rate exceeds 6° per second, an arrowhead is added to the end of the tape to show that the rate of turn has exceeded the limits of the instrument.

### 4.3.12. Map Underlays

The map is comprised of symbols depicting the location of flight plan waypoints and legs, airports, VORs, DMEs, NDBs, and intersections. The map is always oriented with magnetic heading up and centered so that the current aircraft position coincides with the aircraft ownship symbol. The current map declutter level and map range is shown on the left side of the lower display (**Figure 4-82**).

- 1 Map Symbols
- 2 Aircraft Ownship Symbol
- 3 Map Declutter Level
- 4 Map Range



Figure 4-82 Map (ARC Compass Mode Shown)

When enabled, the map underlies all other instruments and annunciations in the lower half of the display. The GPS flight plan is rendered in either straight or curved lines, as supported by the configured GPS navigator. The displayed symbol set includes active waypoints, active flight plan leg, flight plan waypoints, flight plan legs, airports, VORs, VORTACs, TACANs, DMEs, intersections, and NDBs, and are layered accordingly (**Figure 4-83**). There are five map declutter levels and eleven range levels that determine which symbols and how their identifiers are displayed.

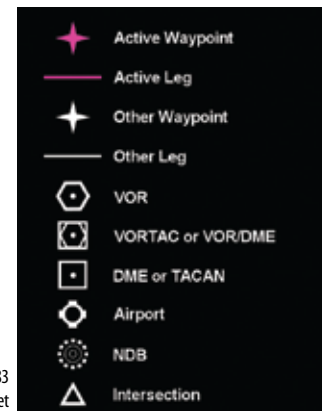


Figure 4-83  
Map Symbol Set

*If connected to a GPS system that does not provide compatible Map data, then only OFF and FP ONLY display levels are available.*



To turn the map on or off, the pilot selects one of the map declutter levels as described in **Section 5.2**. The default map declutter level is HIGH. The map range displays so that the outside radius of the compass represents 2.5, 5, 10, 15, 20, 30, 40, 60, 80, 100, or 200 nautical miles from the aircraft ownship symbol. The default range is 15 NM. Both the map declutter level and range are pilot-adjustable.

- Push the MAP Hot Key (**Figure 4-84**) to cycle through and select the desired map declutter level (**Figure 4-85**).



## Set Map Range

- Press the Range Up (+) or the Range Down (-) Key (**Figure 4-86**) until the desired range is displayed (**Figure 4-87**).



Figure 4-86  
Map Range Keys

### NOTE

The map range increases or decreases one increment each time the +/- button is pressed. To continuously increase/decrease the range, press and hold either button for more than a half second.

### NOTE

Based on the map symbol level and range settings, flight plan waypoints may not be displayed



Figure 4-87  
New Map Range



Figure 4-88 GPS1 Failure, Reversionary Navigation



Figure 4-89 GPS1 Failure, Reversionary Navigation

**NOTE**

*The RSM GPS ENABLED / DISABLED settings are retained following a power cycle of the unit, defaulting to "ENABLE" if not previously set. The RSM GPS usage settings are retained following a power cycle of the unit, defaulting to "EMER ONLY" if not previously set.*



Figure 4-90 Invalid or Failed GPS Annunciations

**4.3.12.2. Flight Plan**

When a flight plan is provided by a configured GPS, the map shows flight plan waypoints and legs. The active leg and waypoint and associated identifier are displayed in magenta. Other waypoints and legs are white. Straight and curved flight plan details are rotated within the map display to maintain their correct compass orientations at all times.

**4.3.12.3. Map Data Source and Reversion**

When configured with compatible GPS equipment, aircraft position, flight plan, and map data are provided by the selected GPS navigation source (either GPS1 or GPS2).

If the aircraft GPS position data is no longer available or becomes invalid:

- The associated flight plan and map data are retained and displayed.
- The flight plan and waypoints become inactive and are displayed in white.
- The aircraft position is provided by:
  1. Another configured GPS source if providing valid position data. In this case, a GPS# REVERSION annunciation is shown above the CDI navigation source select legend (**Figure 4-88**) ("#" indicates the configured GPS source that is now providing the aircraft's position, either 1 or 2).
  2. The RSM GPS, if enabled, and position data are available. In this case, a RSM GPS REVERSION EMER USE ONLY annunciation is shown above the CDI navigation source select legend (**Figure 4-89**).

When a GPS source's position data are invalid or no longer available, an amber annunciation, GPS1, GPS2, or RSM GPS, is shown to the left of the lower display to indicate which has failed (**Figure 4-90**).

### 4.3.13. Track Indicator

When configured with a GPS that provides ground track data, a blue track indicator diamond is displayed on the compass scale to indicate the aircraft's ground track. This indicator may be used to compensate for wind drift during flight (**Figures 4-91 and 4-92**). The track marker is removed from the display when ground track data is unavailable or invalid.



Figure 4-91  
ARC Compass Mode, Ground  
Track Marker



Figure 4-92  
360° Compass Mode, Ground  
Track Marker

## 4.4. Lateral and Vertical Deviation Indicator

In addition to the CDI in the lower display, separate displays of lateral and vertical deviation information are shown in the upper display area during instrument approaches. A Lateral Deviation Indicator (LDI) and a Vertical Deviation Indicator (VDI) (**Figure 4-93**) will automatically appear, depending on the operating mode of the selected navigation sensor and the validity of the associated signal, described below.

- 1 Vertical Deviation Indicator (VDI)
- 2 Lateral Deviation Indicator (LDI)
- 3 LDI Source Indicator

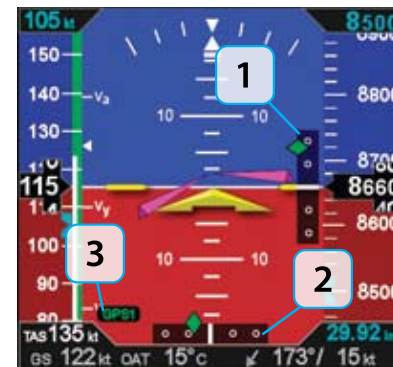


Figure 4-93  
Lateral and Vertical Deviation Indicators



Figure 4-94  
Lateral Deviation Indicator Exceed



Figure 4-95 LDI  
Source Invalid

#### 4.4.1. Lateral Deviation Indicator

The LDI automatically displays when:

- The active navigation source is a GPS radio and the GPS is in approach mode and valid.
- Or
- The active navigation source is a VHF navigation radio and a valid LOC, LOC(BC), or ILS signal is received.

When the LOC(BC) mode is active, deviation indications (corrected for reverse sensing) are displayed. The deviation shown on the LDI directly corresponds to the deviation indicated on the CDI in the lower display. When the lateral deviation exceeds the displayable range of 2.5 dots, the course deviation diamond becomes dim and hollow, and is “parked” at the extreme edge of the LDI scale (**Figure 4-94**).

When the LDI navigation source is invalid or is no longer available, the LDI course deviation indicator symbol is removed from view and the navigation source legend is slashed by a red horizontal line (**Figure 4-95**).



### 4.4.2. Vertical Deviation Indicator

The Vertical Deviation Indicator (VDI) is enabled on the attitude indicator when the active navigation source is a VHF navigation radio, the ILS mode is active, and a valid localizer signal is being received. The VDI is also displayed for a GPS, supplying valid vertical deviation data, when in the approach mode. When the vertical deviation exceeds the displayable range, the course deviation diamond becomes dim and hollow, and is “parked” at the extreme edge of the VDI scale (**Figure 4-96**).

Figure 4-96  
Vertical Deviation  
Indicator Exceed



### 4.5. Vertical Speed Indicator

When the 360° compass is used, the Vertical Speed Indicator (VSI) is rendered, on the right side of the Navigation Display, showing a digital and graphical representation of vertical speed. The VSI indicates non-barometric change in pressure altitude over time. The graphical display is a white vertical tape, with the numerical value at the top of the VSI tape (**Figure 4-97**). In either Arc Compass mode, only the numerical value is shown.

The VSI tape displays rates of  $\pm 2,000$  FPM while the numerical value displays rates up to  $\pm 9,990$  FPM. When vertical speed exceeds  $\pm 2,000$  FPM, a triangle caps the tape (**Figure 4-98**).

Figure 4-97  
Vertical Speed Indicator



Figure 4-98  
VSI Tape Off-Scale  
Marker



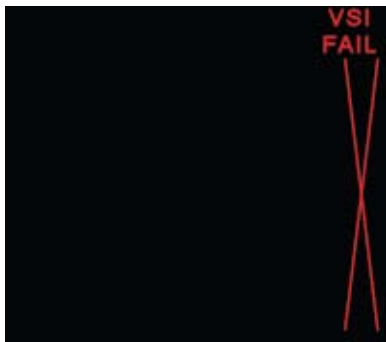


Figure 4-99  
Vertical Speed Indicator Fail – Direction  
Indicator 360° Compass Mode

The VSI tape is nonlinear, giving more display area to the 0 to  $\pm 1,000$  FPM range than to the  $\pm 1,000$  to  $\pm 2,000$  FPM range. Tick marks are presented only in the direction of the climb or descent to provide visual cues for trends. The VSI numerical value, tape, and scale markers are only shown if the aircraft is climbing or descending more than  $\pm 100$  FPM. During level flight in calm air conditions, the tape, scale, scale markers, and zero reference line are removed from the display. The numerical value field is always enabled and shows dashes when vertical rates are out of range. If vertical speed is invalid, the tape and digital display are replaced with a red "X", and the annunciation, VSI FAIL (Figure 4-99).

## 4.6. Autopilot Integration

The EFD1000 can connect with many different legacy autopilot systems that are typically found in general aviation aircraft. The EFD1000 emulates the HSI and/or Flight Director (FD) indicator with which the autopilot was originally certified. Autopilot integration is limited to heading and navigation modes, including vertical approach modes.

When connected to an autopilot system that includes Nav or Approach couplers, the EFD also acts as the navigation source selector switch to the autopilot. This assures that the navigation information presented on the EFD1000 is the same as that being provided to the autopilot. This arrangement also eliminates the need for external autopilot navigation source selector switches and relays that were previously used to select which navigation radio would be connected to the autopilot. Selection of autopilot modes and mode control is unaffected by installation of the EFD1000 system.

The EFD1000 does not currently provide vertical coupling to barometric references such as altitude hold, vertical speed, or altitude capture.

See the upcoming **Section 4.6.3 Typical Autopilot Operation** for additional details on EFD1000 operation with the autopilot systems during typical aircraft operations, such as VOR/ILS/GPS approaches.



### NOTE

*Refer to the autopilot AFMS for information on the operation of the autopilot or flight director.*

**NOTE**

*Refer to the Aircraft Flight Manual Supplement for your GPS system for information about GPSS steering commands that may be output by that system.*

**NOTE**

*When GPSS is selected on the EFD1000, the autopilot must be in Heading mode to follow the GPSS command. The GPSS feature requires installation of the optional ACU.*

### 4.6.1. GPS Steering (GPSS)

GPS Steering represents a modernized approach to flying between flight plan waypoints, and offers many advantages of over traditional methods of flying direct course lines between waypoints.

With traditional point-to-point navigation, the autopilot is provided with desired course and cross-tack deviation information associated with the current flight leg. From there, it will maneuver the aircraft to center the needle and track the desired course. The autopilot does not anticipate upcoming course changes, nor can it fly curved flight paths without pilot assistance, and it has to recompute wind corrections following each course change. Upon reaching a waypoint, the pilot must set the course for the next leg (unless Auto Course Select is enabled, see **Section 4.3.6**), and the autopilot will then intercept and track that leg. In this type of operation, the CDI must always be set to the current desired navigation course.

With GPS Steering, the EFD1000 can unlock the GPS Steering capability already available in many models of General Aviation GPS computers. In GPS systems with this capability, the GPS continually computes the desired bank angle to track the GPS flight plan, and outputs that information over an ARINC 429 data bus. The GPS Steering command includes anticipation of upcoming turns; this includes the turn rate and turn initiation point required to roll out centered on the next leg, with the deviation needle centered.

Some GPS systems, such as the Garmin 4xx/5xxW series of WAAS navigators, even provide GPS Steering commands for complex procedures, such as DME arcs, holding patterns, procedure turns, etc., allowing the autopilot to fly these maneuvers without pilot input. Check with your GPS manufacturer to see if your GPS supports these capabilities.

The EFD1000 translates GPS Steering commands received over an ARINC 429 bus into a signal that is compatible with the autopilot Heading channel. **Thus, by selecting GPSS**

on the EFD1000 and the Heading mode of the autopilot, the autopilot is able to fly GPS Steering commands.

When GPSS is not selected, the autopilot will follow the heading bug value manually set by the pilot.

If the connected GPS system does not provide the required roll steering command, the GPSS legend adjacent to the GPSS Hot Key will be rendered in gray and it will not be possible to enable GPSS operation via the Hot Key.

#### Enable/Disable GPSS

- Press the GPSS Hot Key to alternately Enable or Disable GPS Steering (Figure 4-100).

When GPSS is enabled, the GPSS legend adjacent to the GPSS Hot Key will be shown in green, and when the autopilot is in HDG mode it will follow the steering commands output by the GPS.

When GPSS is disabled, the GPSS legend adjacent to the GPSS Hot Key will be shown in gray, and when the autopilot is in HDG mode it will track the heading selected by the Heading Bug of the EFD1000.



Figure 4-100  
GPSS Hot Key

### 4.6.2. Flight Director

When connected to a compatible autopilot system, the EFD1000 will display a single-cue Flight Director (FD). The flight director command bars visually represent the lateral and vertical steering cues transmitted to the EFD by the autopilot. When the FD output from the autopilot is unavailable or flagged invalid, the FD command bars are removed from the display (Figure 4-101). To hand fly using the flight director, maneuver the airplane to tuck the aircraft reference symbol into the flight director V-bars.



Figure 4-101  
Flight Director

**NOTE**

*When GPSS is enabled on the EFD1000, the HSI heading bug is not coupled to the autopilot. To connect the heading bug to the autopilot, disable GPSS via the GPSS Hot Key.*

**NOTE**

*The autopilot must be in Heading (HDG) Mode to receive GPSS signals from the EFD1000.*

**NOTE**

*When using an integrated VLOC/GPS radio system, select the VLOC or GPS portion of the integrated radio by pressing the CDI source key on the GPS select until the desired source is indicated above the EFD1000 CDI (Section 4.3.5) Source Select button.*

### 4.6.3. Typical Autopilot Operations

Whenever the EFD1000 installed configuration includes connections to GPS, VLOC and autopilot systems, the EFD1000 acts as a conduit of data between the navigation radios and the autopilot system. This configuration enables any navigation sensor available for display on the EFD system to be coupled to the autopilot.

**NOTE**

*Refer to the autopilot system Aircraft Flight Manual Supplement and/or POH for details regarding use and operation of the autopilot system.*

*Examples here are provided for reference only, based on operation of the Bendix/King KFC-200 autopilot, and actual operation may vary depending on the autopilot system installed in your aircraft.*

*It is your responsibility as Pilot in Command to ensure that you are conversant with the operation of all installed equipment. Operation of the EFD1000 system in IMC conditions should not be undertaken unless you are proficient in its use and operation, as described herein.*

**"HDG" Mode Operation – Heading Bug Steering**

1. Set the heading bug on the EFD1000 to the desired heading (**Section 4.3.9**).
2. Verify that GPSS is not selected (GPSS Legend on Hot Keys shown in GRAY).
3. Select the autopilot's HDG mode.
4. Engage the autopilot.
5. Verify that the autopilot turns the aircraft to the selected heading.

**"HDG" Mode Operation – GPS Steering (GPSS)**

1. Couple the EFD1000 CDI to a GPS sensor navigation source with an active flight plan.
2. Enable GPSS by pressing the GPSS Hot Key so that GPSS is rendered in GREEN.
3. Select the autopilot's HDG mode.
4. Engage the autopilot.
5. Verify that the autopilot turns the aircraft to follow the GPS flight plan.

**"NAV" Mode Operation – VLOC Navigation**

1. Using the CDI Nav Source Select button, couple a tuned/valid VLOC radio to the CDI and set the desired course (**Section 4.3.7**).
2. Set the EFD1000 heading bug (**Section 4.3.9**) to a value that will intercept the desired course.
3. Engage the autopilot in heading mode and verify that the aircraft turns to the desired heading.
4. Arm NAV capture on the autopilot by selecting its NAV mode.
5. Monitor the CDI deflection and verify that, upon intercepting the desired course, the autopilot switches to NAV capture, and turns to track the desired course.

**NOTE**

*Not all autopilots operate in the manner described here for intercepting courses. See the AFMS for your autopilot installation to understand how to adapt these example procedures to your particular autopilot.*

**NOTE**

*In order for the autopilot to couple to vertical guidance on WAAS approaches, most autopilots must first be established on the final approach course and in ALT hold mode at least two miles outside the FAF. APPR must be annunciated on the EFD1000 and the GPS system.*

**“NAV” Mode Operation – GPS Navigation**

1. With a valid flight plan programmed and active in the GPS, use the CDI Nav Source Select button to couple the GPS to the CDI (**Section 4.3.5**).
2. If Auto Course Select is disabled, set the Course Pointer to the desired course (4.3.7), or enable Auto Course Select (**Section 4.3.6**).
3. With GPSS disabled, set the EFD1000 heading bug (**Section 4.3.9**) to a value that will intercept the active leg of the flight plan, or enable GPSS via the GPSS Hot Key.
4. Engage the autopilot in HDG mode and verify that the aircraft turns to a heading to intercept the active leg of the flight plan.
5. Arm the NAV mode of the autopilot by selecting its NAV mode.
6. Monitor the CDI deflection and verify that, upon intercepting the flight plan leg, the autopilot switches to NAV Capture and turns to track the desired course.

**“APPR” Mode Operation – ILS Approach with Vectors to Final**

1. Using the CDI Nav Source Select button, couple a tuned/valid ILS radio frequency to the CDI, and set the desired approach course (**Section 4.3.7**).
2. Set the EFD1000 heading bug to a value that will intercept the desired course, or as instructed by ATC (**Section 4.3.9**).
3. Engage the autopilot in HDG and altitude hold (ALT) modes and verify that the aircraft turns to the desired heading.
4. Once cleared for the ILS approach, arm the autopilot’s APPR mode.
5. Monitor the CDI localizer deflection and verify that, upon intercepting the localizer, the autopilot switches to APPR capture, turns to track the localizer course, and arms the glide slope (GS).
6. Monitor the autopilot localizer tracking performance. Upon intercepting the glide slope, verify that the autopilot switches from GS arm to GS capture, and initiates a descent to track the glide slope.



**“APPR” Mode Operation – GPS or GPS/RNAV APV WAAS Approach**

1. With a valid GPS approach programmed in the GPS, use the CDI Nav Source Select button to couple the GPS to the CDI (**Section 4.3.5**).
2. If Auto Course Select is disabled, set the Course Pointer to the desired course (**Section 4.3.7**), or enable Auto Course Select (**Section 4.3.6**).
3. With GPSS disabled, set the EFD1000 heading bug to a value that will intercept the active leg of the flight plan (**Section 4.3.9**) or enable GPSS via the GPSS Hot Key.
4. Once established inbound to the Final Approach Fix (FAF), engage the autopilot’s NAV or APPR mode.
5. Engage the autopilot in HDG mode and verify that the aircraft turns to a heading to intercept the active leg of the approach.
6. Monitor the CDI cross track deviation and verify that, upon intercepting the active leg of the approach, the autopilot turns to track the GPS approach guidance

**THE FOLLOWING APPLIES FOR WAAS GPS/RNAV APV APPROACHES ONLY**

7. Once cleared for the GPS/RNAV approach, arm the autopilot’s APPR mode.
8. Monitor the CDI lateral deviation and verify that, while tracking and/or intercepting the final approach course and once the GPS APPR mode goes active and vertical deviation is presented on the EFD1000’s VDI, the autopilot arms the glide slope.
9. Most WAAS GPS will not arm or activate vertical guidance until the aircraft is within two miles of the FAF (unlike an ILS where the VDI will display as soon as the aircraft is established in-bound and a valid GS signal is being received). As you approach the FAF, watch for the VDI to appear on the EFD1000’s Attitude Display, indicating that the autopilot will likely couple to that glide slope.
9. Monitor the autopilot lateral approach course tracking. Upon intercepting the WAAS glide slope, verify that the autopilot switches from glide slope ARM to glide slope capture, and initiates a descent to track the WASS glide slope.

**NOTE**

WAAS GPS systems can provide vertical guidance on several types of GPS/RNAV instrument approaches. RNAV (GPS) APV (Approaches with Vertical Guidance), such as LPV and LNAV/VNAV approaches, often have lower approach minima shown on the approach plate, and aircraft equipped with appropriate WAAS GPS systems may use those lower minima.

Even with more traditional lateral-guidance-only RNAV (GPS) approaches — (LNAV) with step-down altitudes — WAAS GPS systems may still provide a pseudo-glide slope that enables a continuous descent to the MDA (Minimum Descent Altitude) and that will couple to the autopilot GS.

All these types of approaches are set up and flown the same way by the pilot and autopilot, and operate much like an ILS approach. The pilot must be aware of the differences and which minima may be used, however. Especially in LNAV approaches with advisory vertical guidance, the pilot is still responsible for complying with all interim step-down altitudes and with the MDA.

**NOTE**

The EFD1000 enables GPS LPV approaches (Approaches with Vertical Guidance) by providing the autopilot with GPS lateral and vertical deviation signals that are identical to those typically provided by an ILS radio. To fly GPS LPV approaches, configure and operate the autopilot as you would for an ILS approach.

**NOTE**

Some IFR GPS systems include ILS approaches in their procedures database. GPS may be used to navigate the initial segments of the ILS approach, but the pilot must switch to VLOC navigation outside the FAF and before GS intercept.

Some integrated GPS/nav receivers (like the Garmin 4xx/5xx series) can be configured to do this switch automatically, and the EFD1000 CDI Source will follow that switch automatically. It is the pilot's responsibility to verify that the EFD1000 CDI source is set to VLOC before reaching either GS intercept or the FAF.

### GPS "APPR" Mode Operation – WAAS GPS Underlay to ILS Approach Using Pilot Nav

1. With a valid ILS approach loaded and active in the GPS, use the CDI Nav Source Select button to couple the GPS to the CDI (**Section 4.3.9**).
2. Verify that the correct ILS frequency is tuned.
3. When the active flight plan leg is in-bound to the Initial Approach Fix (IAF), enable GPSS via the GPSS Hot Key.
4. Engage the autopilot in HDG mode, and verify that the aircraft turns to intercept the course to the IAF.
5. Monitor the CDI and aircraft track to ensure the aircraft tracks in-bound to the IAF, and then turns out-bound for the course reversal.
6. Using a WAAS GPS receiver that provides guidance along curved flight paths, the GPS will guide the aircraft through the course reversal and establish it in-bound to the FAF without pilot intervention.
7. Once established inbound to the FAF, engage the autopilot's APPR mode.
8. Couple the EFD1000 to the VLOC source tuned to the correct ILS frequency using the CDI Source Select button (if not done automatically by the GPS/nav receiver).
9. Monitor the CDI localizer deflection and verify that, upon intercepting the localizer, the autopilot switches to APPR capture and arms the GS.
10. Monitor the autopilot localizer tracking performance. Upon intercepting the GS, verify that the autopilot switches from GS ARM to GS capture and initiates a descent to track the glide slope.

### **GPS “APPR” Mode Operation – WAAS GPS Underlay to ILS Approach With ATC Vectors to Final**

1. With a valid ILS approach loaded and active in the GPS, use the CDI Nav Source Select button to couple the GPS to the CDI (**Section 4.3.5**).
2. Verify that the correct ILS frequency is tuned.
3. Set the HDG Bug to the heading assigned by ATC (**Section 4.3.9**).
4. Disable GPSS via the GPSS Hot Key.
5. Engage the autopilot in HDG mode, and verify that the aircraft turns to the selected HDG.
6. When cleared for the approach and given the final heading to intercept the final approach course by ATC, arm the autopilot’s APPR mode.
7. Monitor the CDI and aircraft track to verify that the autopilot intercepts the final approach course and begins to track inbound to the FAF.
8. Couple the EFD1000 to the VLOC source tuned to the correct ILS frequency using the CDI Source Select button (if not done automatically by the GPS/nav receiver).
9. Monitor the CDI localizer deflection and verify that, upon intercepting the localizer, the autopilot switches to APPR capture and arms the GS.
10. Monitor the autopilot localizer tracking performance. Upon intercepting the GS, verify that the autopilot switches from GS ARM to GS capture and initiates a descent to track the glide slope.



## Chapter 5

### Customizing the EFD1000 PFD

#### 5.1. Using the Menu System

There are seven (7) Menu pages, each with up to five (5) menu options. The following tables and figures provide a brief overview of each menu page.

KEY DESCRIPTION		OPTIONS
1	Barometer Setting Units	IN or mB
2	V-speed Textual Markers Display	DISABLE or ENABLE
3	Auto Course Select	DISABLE or ENABLE
4	ARC Compass Mode	HSI or CDI
5	AHRS Reset	Action

Table 5-1 Menu - GENERAL SETTINGS, Page 1 of 7



Figure 5-1  
Menu, Page 1



Figure 5-2  
Menu, Page 2

KEY DESCRIPTION		OPTIONS
1	360° Flight Plan	OFF, AUTO or ON
2	360° Airports	OFF, AUTO or ON
3	360° NDB	OFF, AUTO or ON
4	360° VORs (High, Low and Terminal)	OFF, AUTO or ON
5	360° Intersections	OFF, AUTO or ON

Table 5-2 Menu - 360° MAP SETTINGS, Page 2 of 7

KEY DESCRIPTION		OPTIONS
1	ARC Flight Plan	OFF, AUTO or ON
2	ARC Airports	OFF, AUTO or ON
3	ARC NDB	OFF, AUTO or ON
4	ARC VORs (High, Low and Terminal)	OFF, AUTO or ON
5	ARC Intersections	OFF, AUTO or ON

Table 5-3 Menu - ARC MAP SETTINGS, Page 3 of 7

Figure 5-3  
Menu, Page 3



**NOTE**

For external/battery power control, the legend of the current power source is shown in green; pressing the associated menu key will perform no action. The legend of an available power source is shown in white, and pressing the associated menu key changes input power to that power source.



**NOTE**

When V Speeds are LOCKED at installation the legend and set Value are rendered in gray. Setting any of the above values to zero disables the marker completely.



Figure 5-4  
Menu, Page 4



Figure 5-5  
Menu, Page 5

KEY DESCRIPTION		OPTIONS
1	Va	0 to 450 or LOCKED
2	Vbg	0 to 450 or LOCKED
3	Vref	0 to 450 or LOCKED
4	Vr	0 to 450 or LOCKED
5	Vx	0 to 450 or LOCKED

Table 5-4 Menu - VSPEEDS A, Page 4 of 7

KEY DESCRIPTION		OPTIONS
1	Vy	0 to 450 or LOCKED
2	Vlo	0 to 450 or LOCKED
3	Vle	0 to 450 or LOCKED

Table 5-5 Menu – VSPEEDS B, Page 5 of 7



KEY DESCRIPTION		OPTIONS
1	Operating from or Switch to Battery Power. Green when current state (Pushing key performs no action) White if selection is possible	Status or Action
2	Operating from or Switch to External Power. Green when current state (Pushing key performs no action) White if selection is possible	Status or Action
3	Shut down/Restart (Depending on Air/Ground Logic State)	Action
4	External Power Source Voltage. Displays voltage level of input power	Status Only
5	Internal Battery Status. Displays internal battery % charge and estimated operating time available, ##%/## MIN	Status Only

Table 5-6 Menu – POWER SETTINGS, Page 6 of 7

KEY DESCRIPTION		OPTIONS
1	Main Application Processor Software versions	Status Only
2	Input Output Processor Software Version	Status Only
3	Feature Load	Status Only
4	Unit Serial Number	Status Only

Table 5-7 Menu – SYSTEM STATUS, Page 7 of 7

Figure 5-6  
Menu, Page 6Figure 5-7  
Menu, Page 7

The screenshot shows the ECU display with a tachometer in the center. The tachometer has a green needle pointing to approximately 1500 RPM. The display also shows various engine parameters:
 

- Top left: RPM (1500), TANK (12.5%), and a small 'W' icon.
- Top center: '360' and 'WATER PUMP'.
- Top right: '100' and '100'.
- Right side: A vertical list of parameters with 'AUTO' buttons: '100 AMP', '100', '100', '100', '100', '100', '100', '100'.
- Bottom left: '100' and '100'.
- Bottom center: '100' and '100'.
- Bottom right: '100' and '100'.

## 5.2. Customizing the Map (Declutter)

ON Display symbol is always on.

**AUTO** The selected display level and range, as described in **Table 5-8**, determine which map symbols are displayed. Symbol labels may also display adjacent to their associated symbol.


OFF      Display symbol is always off.

Each compass mode has its own Menu page for Map Setting symbol display. Menu Page 2 offers Map Setting options for the 360° Compass mode (**Figure 5-8**). Menu Page 3 offers Map Setting options for the ARC Compass mode (**Figure 5-9**). The default setting is AUTO. Complete information about the EFD1000 PFD Compass Mode options are provided in **Section 4.3.1**.

## Set Map Symbol Display

1. Push the MENU key. The Menu displays on the Navigation Display.
2. Rotate the Right Knob to navigate to the appropriate Map Settings menu page (either page 2 or 3).
3. Push the desired Map Symbol Menu Key. The menu label turns magenta and the EDIT VALUE label displays above the Right Knob (**Figure 5-10**).
4. Rotate the Right Knob to the desired value (**Figure 5-11**).
5. Either select another Map Symbol Menu Key and edit another display option or push the MENU key to exit the Menu.

Table 5-8  
Map Declutter Levels

LEVEL	DISPLAY	DESCRIPTION												
OFF Fixed	 Figure 5-12 No Map	No symbols, legs, or waypoints - regardless of selected range - are displayed. When selected, the map symbol level and range icons display for two seconds and then are removed from view. The MAP Hot Key legend displays in gray (Figure 5-17).										 Figure 5-17 Map "OFF" Hot Key Legend		
		Range (NM)	2.5	5	10	15	20	30	40	60	80	100	200	
HIGH Variable	 Figure 5-13 High Map	Waypoints	D*	D*	D*	D*	D*	D*	D*	D	D	D	D	
		Airports	D*	D*	D*	D*	D*	D	D	D	D	D		
		NDBs	D*	D*	D*	D	D	D	D					
		VOR/DME - High	D*	D*	D*	D	D	D	D	D	D	D	D	
		VOR/DME - Low	D*	D*	D*	D	D	D	D					
		VOR/DME - Terminal	D*	D*	D*	D	D	D						
		Intersections	D*	D*	D*	D								
MEDIUM Variable	 Figure 5-14 Medium Map	Flight Plan Waypoints	D*	D*	D*	D*	D*	D*	D*	D	D	D	D	
		Airports	D*	D*	D*	D*	D*	D	D	D	D	D		
		VOR/DME - High	D*	D*	D*	D	D	D	D	D	D	D	D	
		VOR/DME - High	D*	D*	D*	D	D	D	D					
LOW Variable	 Figure 5-15 Low Map	Flight Plan Waypoints	D*	D*	D*	D*	D	D	D	D	D	D	D	
		Airports	D*	D*	D*	D*	D*	D	D	D	D	D		
		VOR/DME - High	D*	D*	D*	D	D	D	D	D				
FP ONLY Fixed	 Figure 5-16 Flight Plan Only Map	Only Flight Plan Waypoints display.												
<i>D – symbol displayed</i> <i>D* - symbol displayed with identifier</i>														

## 5.3. Configuring V-speeds

V-speeds are used to designate different operating speeds of the aircraft and are defined in **Table 5-9**.

V-SPEED	DEFINITION	PRE-SET BANDS	ADJUSTABLE TEXT LABELS	PRE-SET MARKERS
Vne	Never exceed	x		x (Red Line)
Vno	Maximum structural cruising rate	x		
Vfe	Maximum full flap extension speed	x		
Vs	No flap stall	x		
Vso	Full flap stall	x		
Va	Maneuvering at maximum gross weight		x	
Vbg	Best glide		x	
Vr	Rotation speed		x	
Vref	Approach speed		x	
Vx	Best angle of climb		x	
Vy	Best rate of climb		x	
Vle	Maximum landing gear extension speed		x	


V-SPEED	DEFINITION	PRE-SET BANDS	ADJUSTABLE TEXT LABELS	PRE-SET MARKERS
Vlo	Retract maximum landing gear operation speed		x	
Vmc	(Multi-engine planes) Single engine minimum control	x		x (Red Line)
Vyse	(Multi-engine planes) Single engine minimum control	x		
	Initial flap extension	x		

Table 5-9 EFD1000 PFD V-speed Definitions

**NOTE**

Setting the value of the white triangle, Vyse, and Vmc markers to zero (0) during installation, disables the markers. Setting any of the adjustable V-speed values to zero (0) disables the applicable label.

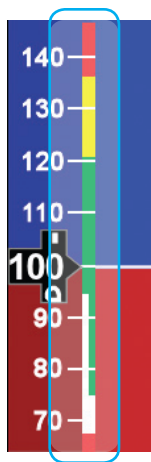


Figure 5-18  
Speed Bands



## NOTE

On aircraft without flaps the white band is disabled, and the green band is shown full width, as there isn't an applicable Flap Extend (Vfe) or Full Flap Stall (Vso) speed. These two speeds are set to the same speed as the No Flap Stall (Vs) speed. This gives the white band a value of zero, effectively disabling it.

The EFD1000 PFD uses colored speed bands, colored speed markers, and textual labels to help the pilot recall V-speed settings and limits. The speed band markings are determined by the Federal Regulations, and correspond to the aircraft limiting speeds that are identified in the Aircraft Flight Manual. They have a range between two speeds, that are pre-set at installation as outlined in **Table 5-10** and shown in **Figure 5-18**.

Speed markers are also pre-set during installation, indicating aircraft specific speed settings, where applicable. The textual V-speed labels are pilot adjustable.

BAND COLOR	SPEED RANGE	
Red Band (High Speed)	Vne - top tape	Never Exceed
Yellow Band	Vno – Vne	Caution Range
Green Band	Vs – Vno	Normal Operating Range
White Band	Vso – Vfe	Flap Operating Range
Red Band (Low Speed)	Bottom of tape – Vs0	Disabled on the ground and during takeoff

Table 5 - 10 Speed Band Ranges





Figure 5-22  
Menu, VSPEEDS A, Page 4 of 7



Figure 5-23  
Editing Va V-speed



Figure 5-24  
Va V-speed Set With New Value

### Set Textual V-speed Labels

1. Push the MENU key. The Menu displays on the Navigation Display.
2. Rotate the Right Knob to navigate to the appropriate V-speed Menu page (either page 4 or 5) (**Figure 5-22**).
3. Push the appropriate V-speed Menu Key. The menu label turns magenta and the EDIT VALUE label displays above the Right Knob (**Figure 5-23**).
4. Rotate the Right Knob to the desired value (**Figure 5-24**).
5. Either select another Menu Key and edit another V-speed or push the MENU key to exit the Menu.



## 5.4. LCD Brightness Control

The LCD brightness of the EFD1000 PFD operates in either of two modes, Automatic or Manual (**Figures 5-25 and 5-26**). The LCD brightness range is displayed as a value from 1 - 100, displayed above the Left Knob. .

LCD MODE	DESCRIPTION
AUTOMATIC BRT AUTO	LCD backlight intensity is automatically adjusted based on the current light conditions sensed by the Automatic Dimming Photocell ( <b>Figure 5-25</b> ). When using the auto-brightness the display brightness will display up to 70%.
MANUAL BRT ADJUST	Allows the pilot to adjust the LCD backlight intensity manually ( <b>Figure 5-26</b> ) from 1 - 100%.

Table 5-11 Brightness Control

### Switch Brightness Mode

1. Press the MENU key. The Menu displays.
2. Push the Left Knob to select the desired LCD Brightness Control mode, either Automatic (BRT AUTO) (**Figure 5-25**), or Manual (BRT ADJUST) (**Figure 5-26**).
3. Press the MENU key. The Menu shuts off.

### Adjust Display Brightness Manually

1. Switch to manual LCD Brightness Control mode (BRT ADJUST) (**Figure 5-26**).
2. Rotate the Left Knob clockwise to increase the LCD Brightness value or counterclockwise to decrease the LCD Brightness value. The BRT value changes accordingly.
3. Press the MENU key. The Menu shuts off and the selected brightness value is retained.



Figure 5-25  
Display Brightness in BRT AUTO Mode

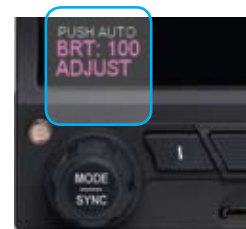


Figure 5-26  
Display Brightness in BRT ADJUST Mode



### NOTE

If the EFD1000 PFD is operating on the internal battery, the maximum brightness level is capped at 40% in automatic mode and 70% in manual mode to preserve emergency battery operating time



### NOTE

To facilitate cooling of the EFD1000 PFD display unit, when the backlight temperature is greater than or equal to 70°C the display brightness caps at 30% in automatic mode and 70% in manual mode. The cap is removed when the EFD1000 PFD display temperature drops below 60°C.



## Chapter 6

# Emergency and Abnormal Procedures

## 6.1. In Flight AHRS Reset

In the unlikely event the EFD1000 PFD determines a potential degradation of attitude information, a warning annunciation, CROSS CHECK ATTITUDE, displays above the aircraft reference symbol (**Figure 6-1**). If the attitude pitch or roll data become invalid, a red "X" and the textual annunciation of "ATTITUDE FAIL" display on the Attitude Indicator and all aircraft roll, pitch, and slip information is removed from the Attitude Indicator display (**Figure 6-2**). Use alternate, mechanical, flight instruments and reset the AHRS as soon as possible.



Figure 6-1  
Attitude Degraded Performance



### NOTE

*When the EFD1000 AHRS is reset in flight, it performs an abbreviated initialization.*

*During the initialization, the aircraft should not be subjected to excessive turn rates. Typical in-flight initialization will take approximately 30 seconds, but can take longer if the reset is initiated while banked or maneuvering.*

*The AHRS reset is considered complete when the EFD1000 attitude and heading is once again displayed, stable, and correct with respect to the horizon or standby indicator.*



Figure 6-2 Attitude Failure



Figure 6-3 Menu, GENERAL SETTINGS,  
Page 1 of 7

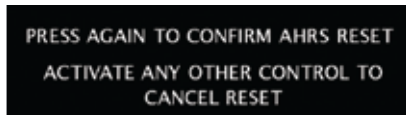


Figure 6-4 AHRS Reset Confirmation  
Message



## NOTE

Pushing any other key, button, or knob cancels the AHRS reset and clears the confirmation message.

## Reset the AHRS

1. Maintain straight and level flight.
2. Push the MENU key. The Menu displays on the Navigation Display.
3. Rotate the Right Knob counterclockwise until Page 1 of the Menu displays (**Figure 6-3**).
4. Push the AHRS Menu Key (Key 5). A confirmation message displays, prompting the user to confirm the reset request (**Figure 6-4**).
5. Push the AHRS Menu Key (Key 5) again to confirm the AHRS reset. The AHRS reset is performed and the confirmation messages clears.
6. Push the MENU key to exit the Menu.

## 6.2. Pitot/Static System Blockage

A static line blockage will result in altitude remaining fixed and a zero vertical speed despite aircraft pitch and/or power setting changes. In addition, IAS indications will be incorrect if the static line is blocked. Errors will typically be noticed in the climb or descent phase of flight. When descending, ambient pressure increases, which will result in the indicated airspeed reading less than the actual airspeed. The opposite effect will be observed in a climb.

A pitot line blockage will result in the airspeed indicator behaving like an altimeter when the aircraft altitude changes, and it does not respond to airspeed changes.

### When Pitot or Static Line is Blocked

1. Select an alternate static source.
2. Set Pitot Heat to ON.



### **CAUTION**

*Most light aircraft have only a single pitot and static port available for flight instrument use. As such, the pitot and static lines used by the EFD1000 system are shared with those lines used by the standby airspeed indicator and altimeter. Should these lines become blocked, such as might occur due to inadvertent icing encounter, both the standby indicators and the EFD1000 indicators will display erroneous airspeed and/or altitude information.*

*In the event of erroneous airspeed and altitude information at the EFD1000, the EFD1000 Attitude Monitor will present a "CROSS CHECK ATTITUDE" annunciation.*

## WARNING

The EFD1000 internal battery will provide approximately 30 minutes of operation for the AHRS and display following loss of aircraft power. If aircraft power cannot be restored, the pilot should follow the electrical failure checklist in the Aircraft Flight Manual.



Figure 6-5 PFD0190 Internal Battery Operational



Figure 6-6 Menu, POWER SETTINGS, Page 6 of 7, Key 1

## 6.3. Loss of External Power

In the event that external power to the unit is degraded or fails, the EFD1000 will automatically switch to its internal battery. When operating on internal battery, the display backlight intensity is capped at a value of 40% for auto dimming and 70% for manual dimming. An annunciation of this operating state and the estimated battery charge remaining is displayed in the lower portion of the attitude indicator (**Figure 6-5**).



### CAUTION

*During situations where a high electrical demand is placed on the aircraft electrical system, electrical transients that cause aircraft voltage to momentarily drop below  $12.5 \pm 0.3V$  (14V Electrical System) or  $25.0 \pm 0.6V$  (28V Electrical System) will cause the EFD to automatically switch to its internal battery.*

*This will be accompanied by an "ON BAT" annunciation.*

*The "ON BAT" annunciation should extinguish shortly after the electric transient demand goes away. If the "ON BAT" annunciation does not extinguish then an external power source failure has most likely occurred.*

## 6.4. Power Override

### To Override the Automatic Power Configuration

1. Push the MENU Key. The Menu displays on the Navigation Display.
2. Rotate the Right Knob until Page 6 of the Menu displays.
3. The current power source is listed at Key 1 (**Figure 6-6**), push Key 1 to alternately switch between external power (EXT PWR) and the internal battery (BATTERY).
4. Push the MENU key to exit the Menu.

### View External Power Status

1. Push the MENU Key. The Menu displays on the Navigation Display.
2. Rotate the Right Knob until Page 6 of the Menu displays.
3. The EXT PWR Menu Key (Key 2, **Figure 6-7**) displays whether the EFD1000 is operating on external power (EXT PWR).
4. Push the MENU key to exit the Menu.

### View External Voltage Status

1. Push the MENU Key. The Menu displays on the Navigation Display.
2. Rotate the Right Knob until Page 6 of the Menu displays.
3. The EXT PWR Menu Key (Key 4, **Figure 6-8**) displays the external power voltage.
4. Push the MENU key to exit the Menu.

### View Internal Battery Status

1. Push the MENU Key. The Menu displays on the Navigation Display.
2. Rotate the Right Knob until Page 6 of the Menu displays.
3. The BAT Menu Key (Key 5, **Figure 6-9**) displays the current battery status as a percentage of charge and estimated operating time available (##%/## MIN).
4. Push the MENU key to exit the Menu.



### NOTE

*When airborne, if the EFIS input voltage is below the  $12.5 \pm 0.3V$  (14V Electrical System) or  $25.0 \pm 0.6V$  (28V Electrical System) automatic battery transition threshold, and "EXT PWR" is selected the EFD will automatically transition back to its internal battery.*



Figure 6-7  
Menu, POWER SETTINGS,  
Page 6 of 7,  
EXT PWR Menu Key (Key 2)



Figure 6-8  
Menu, POWER SETTINGS,  
Page 6 of 7,  
EXT PWR Menu Key (Key 4)



Figure 6-9  
Menu, POWER SETTINGS,  
Page 6 of 7,  
BAT Menu Key (Key 5)

## 6.5. Abnormal Shutdown Procedure

The EFD1000 PFD is typically powered through an EFIS Power Control switch that is connected to the aircraft battery bus. The system will power up, based on the position of the EFIS Power Control switch or switch that controls power to the Battery bus. Typically, when on the ground, powering up/down the aircraft simultaneously powers on/off the EFD1000 PFD. If the EFD1000 PFD has been powered off and aircraft power is available to the EFD1000 PFD, pressing the REV button momentarily will turn on the EFD1000 PFD.

### **Power Off Manually**

1. Pull the circuit breaker.
2. Press and hold the REV key until the EFD1000 PFD powers off.

Or




1. Press the MENU key. The Menu displays.
2. Rotate the Right Knob to display Page 6 of 7, POWER SETTINGS.
3. Press Menu Key 3, SHUT DOWN. The power down sequence initiates.



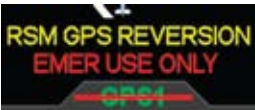


### **Power On Manually**

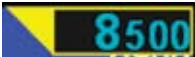





- Press the REV key until the EFD1000 PFD powers on.



## 6.6. Warning, Caution, and Advisory Summary

WARNINGS		
ON BAT	 <p>Figure 6-10 WARNING - On Battery</p>	Red annunciation presented whenever the EFD1000 is operating on the internal battery. Will be accompanied by an indication of the estimated battery life remaining.
Function FAIL ("X")	 <p>Figure 6-11 WARNING - Attitude Fail</p>  <p>Figure 6-12 WARNING - Direction Indicator Fail</p>	Red annunciation presented whenever the EFD1000 has determined that the associated function is invalid or failed and should not be used. The data is removed from the display and replaced by a red "X" over the affected display feature.

CAUTIONS			
CROSS CHECK ATTITUDE		Figure 6-13 CAUTION - Cross Check Attitude	Amber annunciation presented, centered in the upper half of the attitude indicator, whenever the EFD1000 AHRS internal integrity monitor determines that attitude is potentially degraded. If a CROSS CHECK ATTITUDE annunciation is provided, the pilot should cross check attitude, airspeed, and altitude against the standby displays.
GPS1, GPS 2, and/or RSM GPS		Figure 6-14 CAUTION - GPS1, GPS 2, and/or RSM GPS	Amber annunciation presented on the left edge of the display to indicate when a configured GPS flight plan and mapping data are invalid or not available.
RSM GPS REVERSION EMER USE ONLY		Figure 6-15 CAUTION - RSM GPS Reversion	Amber annunciation presented whenever the EFD1000 reverts to RSM GPS data and indicates that the RSM GPS is the current GPS source. RSM GPS usage is limited to EMER USE ONLY.
INTEG		Figure 6-16 CAUTION - INTEG	Amber annunciation presented when the GPS source coupled to the HSI “flags” the GPS integrity. See the GPS AFMS for more information.
MINIMUMS		Figure 6-17 CAUTION - Minimums	Amber annunciation presented whenever the aircraft is at or below the MINIMUMS altitude set by the pilot. May be accompanied by an optional one-second stuttered tone.

ADVISORY			
Altitude Alerter		Figure 6-18 ADVISORY - Altitude Alerter	Amber flag presented to indicate the aircraft is reaching (steady) or deviating (flashing) from the preselected altitude. May be accompanied by an optional one-second steady tone.
DH Alert		Figure 6-18 ADVISORY - Decision Height Alert	Yellow "DH" annunciation provided whenever a connected radio altimeter indicates it has reached the altitude set by the pilot. See the Radio Altimeter AFMS for more information.
GPS Annunciations: APPR, WPT, MSG		Figure 6-18 ADVISORY - GPS Annunciations	Green Annunciations associated with the GPS coupled to the HSI. See the GPS AFMS for more information.
INVALID DATA			
Slashing red line	  	Figure 6-21 INVALID DATA - Slashing Red Line	A horizontal or vertical red line through the source legend of selected data indicates that the data are invalid or unavailable.



# Chapter 7

## Appendices

### 7.1. Operating Limitations

The Aspen EFD1000 PFD Airplane Flight Manual Supplement, A-01-175-00 Revision B (or later FAA Approved revision), contains the limitations that apply to your specific aircraft installations, and must be immediately available to the flight crew when the EFD1000 PFD is being used to provide flight or navigation information. The following are summary, advisory information that apply to most EFD1000 PFD installations.

#### 7.1.1. Weight & Center of Gravity

Installation of the EFD1000 system may result in a small net change to the aircraft empty weight and associated moment arm. Refer to the revised weight and balance records carried in the aircraft for details.

#### 7.1.2. RSM GPS Usage

The EFD1000 RSM GPS is authorized for emergency use only. Position data from the RSM GPS will ONLY be presented following the loss or failure of a certified external GPS navigator.

#### 7.1.3. Geographic Limitation

Like all compass systems, the magnetometer used in the EFD1000 system will experience degraded performance in the vicinity of the magnetic poles. When the



#### NOTE

*When the RSM GPS is in use, magnetic variation data used by the map is not updated. This can result in misaligned map symbology whenever the external GPS position source is lost and the aircraft travels far enough to produce a significant change in the local magnetic variation.*

horizontal component of the earth's magnetic field is no longer strong enough to provide reliable heading data, the EFD1000 System will present a "CROSS CHECK ATTITUDE" annunciation, and will subsequently flag the magnetometer data as invalid, resulting in the annunciated loss of heading and attitude. Depending on the aircraft latitude and longitude, this effect could be observed as far away as 750 nm from the magnetic pole. In the Northern Hemisphere, this equates to operations in the Arctic Islands found north of continental North America

Use of the EFD1000 system for IFR operations within 750 nautical miles of the Magnetic Poles, based solely upon the attitude and heading data provided by the EFD1000, is prohibited.

#### **7.1.4. Placards and Decals**

The following electronic placard is provided on the EFD1000 display whenever the RSM GPS is providing position data for the map display:

"RSM GPS REVERSION  
EMER USE ONLY"

#### **7.1.5. Seaplane Operation**

The EFD1000 system may not be able to align when on water as a function of the wave action being experienced by the aircraft. When aligning on water, always perform a visual verification of the attitude reference with a secondary source, such as a mechanical gyro or the horizon. If the alignment is not successful, it is acceptable to depart under VFR/VMC and, while maintaining VFR/VMC, perform an AHRS in flight alignment.

## 7.2. Software Versions

The system software version for the Main Application Processor (MAP) and for the Input-Output Processor (IOP), both of which are contained within the EFD display unit, is displayed via the Menu SYSTEM STATUS page. The ACU software version number is recorded on a software version label affixed to the ACU hardware.

### To View the Main Application Processor Software Version

1. Push the MENU Key. The Menu displays on the Navigation Display.
2. Rotate the Right Knob until Page 7 of the Menu displays.
3. The MAP VER Menu Key (Key 1) displays the current Main Application Processor Software Version (**Figure 7-1**).
4. Push the MENU key to exit the Menu.

### To View the Input/Output Processor Software Version

1. Push the MENU Key. The Menu displays on the Navigation Display.
2. Rotate the Right Knob until Page 7 of the Menu displays.
3. The IOP VER Menu Key (Key 2) displays the current Input/Output Processor Software Version (**Figure 7-2**).
4. Push the MENU key to exit the Menu.

Figure 7-1  
Menu, SYSTEMS STATUS, Page 7 of 7



Figure 7-2  
Menu, SYSTEMS STATUS, Page 7 of 7





Figure 7-3  
Menu, SYSTEMS STATUS, Page 7 of 7



Figure 7-4  
Menu, SYSTEMS STATUS, Page 7 of 7

### To View the Feature Load

1. Push the MENU Key. The Menu displays on the Navigation Display.
2. Rotate the Right Knob until Page 7 of the Menu displays.
3. The FEATURES Menu Key (Key 3) displays the current Feature Load (**Figure 7-3**).
4. Push the MENU key to exit the Menu.

### To View the Unit Serial Number

1. Push the MENU Key. The Menu displays on the Navigation Display.
2. Rotate the Right Knob until Page 7 of the Menu displays.
3. The S/N Menu Key (Key 4) displays the unit's serial number(**Figure 7-4**).
4. Push the MENU key to exit the Menu.



## 7.3. Specifications

### 7.3.1. EFD1000 Display Unit

GENERAL SPECIFICATIONS:	
Width	3.50 in. (Measured at Bezel)
Height	7.00 in. (Measured at Bezel)
Can Depth	4.15 in. (Rear of Bezel to Rear of Can)
Overall Depth	6.35 in. (Knob to Rear Pressure Fitting)
Weight	2.9 lbs (with Mounting Bracket)
Display Type	6.0 in. Diagonal TFT Active Matrix LCD (400x760)
Display Colors	32,768
Face	Anti-Reflective Coated Glass
Backlight	High Intensity White LED
Rotary Knobs	Optical Encoder with Momentary Push
Dimming	Manual & Automatic (Front Bezel Mounted Sensor)
OPERATIONAL SPECIFICATIONS:	
Operating Temp	-20°C to +55°C
Storage Temp	-55°C to +85°C
Max Un-Pressurized Operating Altitude	35,000 ft
Max Pressurized Operating Altitude	55,000 ft
Cooling	Integral Fan
Max Humidity	95% at 50°C

Input Voltage	+8 to +32 Volts DC
Max Current	2.4 Amps @ 28 Vdc
	4.8 Amps @ 14 Vdc
<b>I/O SPECIFICATIONS:</b>	
ARINC 429 Inputs	5 Low Speed
ARINC 429 Outputs	1 Low Speed
RS-232 Inputs	5
RS-232 Outputs	3
Pitot / Static	Quick Connect
<b>CERTIFICATION SPECIFICATIONS:</b>	
Technical Standard Order	TSO-C2d    Airspeed Instruments TSO-C3d    Turn and Slip Instrument TSO-C4c    Bank and Pitch Instruments TSO-C6d    Direction Instrument Magnetic (Gyroscopically Stabilized) TSO-C8d    Vertical Velocity Instrument (Rate of Climb) TSO-C10b   Altitude Pressure Activated Sensitive Type TSO-C106   Air Data Computer TSO-C113   Airborne Multipurpose Electronic Displays
Software	RTCA DO-178B Level C
Environmental	RTCA DO-160E
Categories	See Environmental Qualification Sheet found in the installation manual.

Table 7-2 EFD1000 Display Unit Specifications

### 7.3.2. Remote Sensor Module (RSM)

Width	2.65 in.
Length	4.40 in
Height	1.00 in.
Weight	0.2 lbs
Input Voltage	Provided by EFD1000
Max Current	Included in EFD1000 Current

Table 7-3 Remote Sensor Module (RSM) Specifications

### 7.3.3. Analog Converter Unit (ACU)

Width	5.75 in. (including mounting flange)
Length	4.30 in. (including connector)
Height	1.60 in. (including mounting flange)
Weight	0.8 lbs
Input Voltage	+10 to +32 Volts DC
Max Current	0.5 Amps @ 28 Vdc 1.0 Amps @ 14 Vdc
Interfaces	ARINC-429 and RS-232

Table 7-4 Analog Converter Unit (ACU) Specifications

### 7.3.4. Operational Specifications

Airspeed Range	Minimum displayed airspeed	20 KIAS
	Maximum displayed airspeed	999 KIAS
Altitude Range	Minimum displayed altitude	-1,500 ft MSL
	Maximum displayed altitude	60,000 ft MSL
Vertical Speed Range	Maximum displayed vertical speed rates (tape)	+/-2,000 fpm
	Maximum displayed vertical speed rates (numerical value)	+/- 9,990 fpm
Turn Rate	Maximum displayed turn rate	4.5 °/second
Barometric Pressure Correction Range	28.10 to 30.99 InHg (946 to 1049 mB)	
Internal Battery	Minimum operating time while on internal battery	30 minutes

Table 7-5 Operational Specifications

## 7.4. Acronyms and Abbreviations

A/D	Analog to Digital
AC	Alternating Current
ACU	Analog Converter Unit
ADC	Air Data Computer
ADI	Attitude Director Indicator
AFMS	Airplane Flight Manual Supplement
AHRS	Attitude Heading Reference System
AI	Attitude Indicator
AP or A/P	Autopilot
APPR	Approach
ARC	Partial heading arc format (100°)
ARINC	Aeronautical Radio Inc.
BC	Back Course
BP	Bearing Pointer
CDI	Course Deviation Indicator
CFR	Code of Federal Regulations
CM	Configuration Module
CRS	Course
DC	Direct Current
DH	Decision Height
DME	Distance Measuring Equipment
EEPROM	Electrically Erasable Programmable Read-Only Memory
EFD	Evolution Flight Display

EFIS	Electronic Flight Instrument System
FAF	Final Approach Fix
FD	Flight Director
ft	Feet
GPS	Global Positioning System
GPSS	GPS Steering
GS	Glide slope
HSI	Horizontal Situation Indicator
Hz	Hertz (frequency)
IAF	Initial Approach Fix
IAS	Indicated Air Speed
IFR	Instrument Flight Rules
ILS	Instrument Landing System
IMC	Instrument Meteorological Conditions
IOP	Input/Output Processor
KIAS	Knots Indicated Air Speed
kts	Knots
lb	pound
LCD	Liquid Crystal Display
LDI	Lateral Deviation Indicator
LOC	Localizer
mA	milliamp, 0.001 ampere
MAP	Main Application Processor
MFD	Multi-Function Display

ms	millisecond
MSG	Message
MSL	Mean Sea Level
NDB	Non-Directional Beacon
nm	Nautical Miles
OAT	Outside Air Temperature
OBS	Omni-Bearing Selector
PFD	Primary Flight Display
RMI	Radio Magnetic Indicator
RSM	Remote Sensor Module
RSS	Roll Sum Steering
TAS	True Air Speed
TERM	Terminal Mode
Vac	volts, alternating current
Vdc	volts, direct current
VDI	Vertical Deviation Indicator
VHF	Very High Frequency
VLOC	VOR/Localizer
VOR	VHF Omni-Directional Radio Range
VSI	Vertical Speed Indicator
WPT	Waypoint

## 7.5. Index

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